## D02TZF - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

# 1 Purpose

D02TZF returns information about the solution of a general two point boundary value problem computed by D02TKF.

# 2 Specification

SUBROUTINE DO2TZF(MXMESH, NMESH, MESH, IPMESH, ERMX, IERMX,

1 IJERMX, RWORK, IWORK, IFAIL)

INTEGER MXMESH, NMESH, IPMESH(MXMESH), IERMX, IJERMX,

1 IWORK(\*), IFAIL

real MESH(MXMESH), ERMX, RWORK(\*)

# 3 Description

D02TZF and its associated routines (D02TVF, D02TKF, D02TXF and D02TYF) solve the two point boundary value problem for a nonlinear mixed order system of ordinary differential equations

$$\begin{array}{rcl} y_1^{(m_1)}(x) & = & f_1(x,y_1,y_1^{(1)},\ldots,y_1^{(m_1-1)},y_2,\ldots y_n^{(m_n-1)}) \\ y_2^{(m_2)}(x) & = & f_2(x,y_1,y_1^{(1)},\ldots,y_1^{(m_1-1)},y_2,\ldots y_n^{(m_n-1)}) \\ & & & & & & & & \\ y_n^{(m_n)}(x) & = & f_n(x,y_1,y_1^{(1)},\ldots,y_1^{(m_1-1)},y_2,\ldots y_n^{(m_n-1)}) \end{array}$$

over an interval [a,b] subject to  $p \ (>0)$  nonlinear boundary conditions at a and  $q \ (>0)$  nonlinear boundary conditions at b, where  $p+q=\sum_{i=1}^{n}m_{i}$ . Note that  $y_{i}^{(m)}(x)$  is the m-th derivative of the i-th solution component. Hence  $y_{i}^{(0)}(x)=y_{i}(x)$ . The left boundary conditions at a are defined as

$$g_i(z(y(a))) = 0, \quad i = 1, 2, \dots, p,$$

and the right boundary conditions at b as

$$\bar{g}_j(z(y(b))) = 0, \quad j = 1, 2, \dots, q,$$

where  $y = (y_1, y_2, \dots, y_n)$  and

$$z(y(x)) = (y_1(x), y_1^{(1)}(x), \dots, y_1^{(m_1-1)}(x), y_2(x), \dots, y_n^{(m_n-1)}(x)).$$

First, D02TVF must be called to specify the initial mesh, error requirements and other details. Then, D02TKF can be used to solve the boundary value problem. After successful computation, D02TZF can be used to ascertain details about the final mesh. D02TYF can be used to compute the approximate solution anywhere on the interval [a, b] using interpolation.

The routines are based on modified versions of the codes COLSYS and COLNEW, [2] and [1]. A comprehensive treatment of the numerical solution of boundary value problems can be found in [3] and [5].

## 4 References

- [1] Ascher U M and Bader G (1987) A new basis implementation for a mixed order boundary value ODE solver SIAM J. Sci. Stat. Comput. 8 483–500
- [2] Ascher U M, Christiansen J and Russell R D (1979) A collocation solver for mixed order systems of boundary value problems *Math. Comput.* **33** 659–679

- [3] Ascher U M, Mattheij R M M and Russell R D (1988) Numerical Solution of Boundary Value Problems for Ordinary Differential Equations Prentice Hall, Englewood Cliffs, NJ
- [4] Cole J D (1968) Perturbation Methods in Applied Mathematics Blaisdell, Waltham, Mass.
- [5] Keller H B (1992) Numerical Methods for Two-point Boundary-value Problems Dover, New York

### 5 Parameters

#### 1: MXMESH — INTEGER

Input

On entry: the maximum number of points allowed in the mesh.

Constraint: this must be identical to the value supplied for the argument MXMESH in the prior call to D02TVF.

2: NMESH — INTEGER

Output

On exit: the number of points in the mesh last used by D02TKF.

3: MESH(MXMESH) - real array

Output

On exit: MESH(i) contains the i-th point of the mesh last used by D02TKF, for  $i=1,2,\ldots,$ NMESH. MESH(1) will contain a and MESH(NMESH) will contain b. The remaining elements of MESH are not initialized.

4: IPMESH(MXMESH) — INTEGER array

Output

On exit: IPMESH(i) specifies the nature of the point MESH(i), i = 1, 2, ..., NMESH, in the final mesh computed by D02TKF.

IPMESH(i) = 1 indicates that the *i*-th point is a fixed point and was used by the solver prior to an extrapolation-like error test.

IPMESH(i) = 2 indicates that the *i*-th point was used by the solver prior to an extrapolation-like error test.

 $\mathrm{IPMESH}(i) = 3$  indicates that the *i*-th point was used by the solver only as part of an extrapolation-like error test.

The remaining elements of IPMESH are initialized to -1.

See Section 8 for advice on how these values may be used in conjunction with a continuation process.

5: ERMX — real

Output

On exit: an estimate of the maximum error in the solution computed by D02TKF, that is

$$ERMX = \max \frac{\|y_i - v_i\|}{(1.0 + \|v_i\|)}$$

where  $v_i$  is the approximate solution for the *i*-th solution component. If D02TKF returned successfully with IFAIL = 0, then ERMX will be less than TOLS(IJERMX) where TOLS contains the error requirements as specified in Section 3 of the document for D02TVF and Section 5 of the document for D02TVF.

If D02TKF returned with IFAIL = 5, then ERMX will be greater than TOLS(IJERMX).

If D02TKF returned any other value for IFAIL then an error estimate is not available and ERMX is initialized to 0.0.

**6:** IERMX — INTEGER

Output

On exit: indicates the mesh sub-interval where the value of ERMX has been computed, that is [MESH(IERMX),MESH(IERMX+1)].

If an estimate of the error is not available then IERMX is initialized to 0.

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#### 7: IJERMX — INTEGER

Output

On exit: indicates the component i (= IJERMX) of the solution for which ERMX has been computed, that is the approximation of  $y_i$  on [MESH(IERMX),MESH(IERMX+1)] is estimated to have the largest error of all components  $y_i$  over mesh sub-intervals defined by MESH.

If an estimate of the error is not available then IJERMX is initialized to 0.

#### 8: RWORK(\*) — real array

Input/Output

On entry: this must be the same array as supplied to D02TKF and **must** remain unchanged between calls.

On exit: contains information about the solution for use on subsequent calls to associated routines.

#### 9: IWORK(\*) — INTEGER array

Input/Output

On entry: this must be the same array as supplied to D02TKF and **must** remain unchanged between calls.

On exit: contains information about the solution for use on subsequent calls to associated routines.

#### 10: IFAIL — INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error or gives a warning (see Section 6).

For this routine, because the values of output parameters may be useful even if IFAIL  $\neq 0$  on exit, users are recommended to set IFAIL to -1 before entry. It is then essential to test the value of IFAIL on exit. To suppress the output of an error message when soft failure occurs, set IFAIL to 1.

# 6 Errors and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors detected by the routine:

IFAIL = 1

On entry, an illegal value for MXMESH was specified, or an invalid call to D02TZF was made, for example without a previous call to the solver routine D02TKF. If on entry IFAIL = 0 or -1, the precise form of the error will be detailed on the current error message unit (as defined by X04AAF).

IFAIL = 2

The solver routine D02TKF did not converge to a solution or did not satisfy the error requirements. The last mesh computed by D02TKF has been returned by D02TZF. This mesh should be treated with extreme caution as nothing can be said regarding its quality or suitability for any subsequent computation.

# 7 Accuracy

Not applicable.

## 8 Further Comments

Note that

if D02TKF returned IFAIL = 0, 4 or 5 then it will always be the case that IPMESH(1) = IPMESH(NMESH) = 1;

if D02TKF returned IFAIL = 0 or 5 then it will always be the case that IPMESH(i) = 3, i = 2, 4, ..., NMESH-1 and IPMESH(i) = 1 or 2, i = 3, 5, ..., NMESH-2.

if D02TKF returned IFAIL = 4 then it will always be the case that IPMESH(i) = 1 or 2, i = 2, 3, ..., NMESH-1.

If D02TZF returns the value IFAIL = 0, then examination of the mesh may provide assistance in determining a suitable starting mesh for D02TVF in any subsequent attempts to solve similar problems.

If the problem being treated by D02TKF is one of a series of related problems (for example, as part of a continuation process), then the values of IPMESH and MESH may be suitable as input parameters to D02TXF. Using the mesh points not involved in the extrapolation error test is usually appropriate. IPMESH and MESH should be passed unchanged to D02TXF but NMESH should be replaced by (NMESH+1)/2.

If D02TZF returns the value IFAIL = 2, nothing can be said regarding the quality of the mesh returned. However, it may be a useful starting mesh for D02TVF in any subsequent attempts to solve the same problem.

If D02TKF returns the value IFAIL = 5, this corresponds to the solver requiring more than MXMESH mesh points to satisfy the error requirements. If MXMESH can be increased and the preceding call to D02TKF was not part, or was the first part, of a continuation process then the values in MESH may provide a suitable mesh with which to initialize a subsequent attempt to solve the same problem. If it is not possible to provide more mesh points then relaxing the error requirements by setting TOL(IJERMX) to ERMX might lead to a successful solution. It may be necessary to reset the other components of TOL. Note that resetting the tolerances can lead to a different sequence of meshes being computed and hence to a different solution being computed.

# 9 Example

The following example is used to illustrate the use of fixed mesh points, simple continuation and numerical approximation of a Jacobian. See also D02TKF, D02TVF, D02TXF and D02TYF, for the illustration of other facilities.

Consider the Lagerstrom-Cole equation

$$y'' = (y - yy')/\epsilon$$

with the boundary conditions

$$y(0) = \alpha \quad y(1) = \beta,$$

where  $\epsilon$  is small and positive. The nature of the solution depends markedly on the values of  $\alpha, \beta$ . See [4].

We choose  $\alpha = -\frac{1}{3}$ ,  $\beta = \frac{1}{3}$  for which the solution is known to have corner layers at  $x = \frac{1}{3}, \frac{2}{3}$ . We choose an initial mesh of seven points [0.0, 0.15, 0.3, 0.5, 0.7, 0.85, 1.0] and ensure that the points x = 0.3, 0.7 near the corner layers are fixed, that is the corresponding elements of the array IPMESH are set to 1. First we compute the solution for  $\epsilon = 1.0\text{E}-4$  using in GUESS the initial approximation  $y(x) = \alpha + (\beta - \alpha)x$  which satisfies the boundary conditions. Then we use simple continuation to compute the solution for  $\epsilon = 1.0\text{E}-5$ . We use the suggested values for NMESH, IPMESH and MESH in the call to D02TXF prior to the continuation call, that is only every second point of the preceding mesh is used and the fixed mesh points are retained.

Although the analytic Jacobian for this system is easy to evaluate, for illustration the procedure FJAC uses central differences and calls to FFUN to compute a numerical approximation to the Jacobian.

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## 9.1 Program Text

**Note.** The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
DO2TZF Example Program Text
Mark 17 Release. NAG Copyright 1995.
.. Parameters ..
TNTEGER.
                 NOUT
PARAMETER
                 (NOUT=6)
INTEGER
                 NEQ, MMAX, NLBC, NRBC, NCOL, MXMESH
                 (NEQ=1,MMAX=2,NLBC=1,NRBC=1,NCOL=5,MXMESH=50)
PARAMETER.
INTEGER
                 LRWORK, LIWORK
PARAMETER
                 (LRWORK=MXMESH*(109*NEQ**2+78*NEQ+7),
                 LIWORK=MXMESH*(11*NEQ+6))
.. Scalars in Common ..
                 ALPHA, BETA, EPS
real
.. Local Scalars ..
real
                 ERMX
INTEGER
                 I, IERMX, IFAIL, IJERMX, J, NMESH
LOGICAL
                 FAILED
.. Local Arrays ..
                 MESH(MXMESH), TOL(NEQ), WORK(LRWORK),
real
                 Y(NEQ,0:MMAX-1)
                 IPMESH(MXMESH), IWORK(LIWORK), M(NEQ)
INTEGER
.. External Subroutines ..
EXTERNAL
                 DO2TKF, DO2TVF, DO2TXF, DO2TYF, DO2TZF, FFUN,
                 FJAC, GAFUN, GAJAC, GBFUN, GBJAC, GUESS
.. Common blocks ..
                 /PROBS/EPS, ALPHA, BETA
.. Executable Statements ..
WRITE (NOUT,*) 'DO2TZF Example Program Results'
WRITE (NOUT,*)
NMESH = 7
MESH(1) = 0.0e0
MESH(2) = 0.15e0
MESH(3) = 0.3e0
MESH(4) = 0.5e0
MESH(5) = 0.7e0
MESH(6) = 0.85e0
MESH(NMESH) = 1.0e0
IPMESH(1) = 1
IPMESH(2) = 2
IPMESH(3) = 1
IPMESH(4) = 2
IPMESH(5) = 1
IPMESH(6) = 2
IPMESH(NMESH) = 1
ALPHA = -1.0e0/3.0e0
BETA = 1.0e0/3.0e0
TOL(1) = 1.0e-5
EPS = 1.0e-3
M(1) = 2
IFAIL = 0
CALL DO2TVF(NEQ,M,NLBC,NRBC,NCOL,TOL,MXMESH,NMESH,MESH,IPMESH,
            WORK, LRWORK, IWORK, LIWORK, IFAIL)
IFAIL = -1
D0 \ 40 \ J = 1, 2
   EPS = 0.1e0*EPS
```

```
WRITE (NOUT, 99997) TOL(1), EPS
        IFAIL = -1
        CALL DO2TKF (FFUN, FJAC, GAFUN, GBFUN, GAJAC, GBJAC, GUESS, WORK, IWORK,
                    IFAIL)
        FAILED = IFAIL .NE. O
        IFAIL = 0
        CALL DO2TZF(MXMESH, NMESH, MESH, IPMESH, ERMX, IERMX, IJERMX, WORK,
                   IWORK, IFAIL)
        WRITE (NOUT, 99996) NMESH, ERMX, IERMX, IJERMX
        IF (FAILED) GO TO 60
        WRITE (NOUT, 99999)
        DO 20 I = 1, NMESH, 2
           CALL DO2TYF(MESH(I),Y,NEQ,MMAX,WORK,IWORK,IFAIL)
           WRITE (NOUT, 99998) MESH(I), Y(1,0), Y(1,1)
  20
        CONTINUE
        IF (J.LT.2) THEN
           NMESH = (NMESH+1)/2
           CALL DO2TXF(MXMESH, NMESH, MESH, IPMESH, WORK, IWORK, IFAIL)
        END IF
  40 CONTINUE
  60 CONTINUE
     STOP
99999 FORMAT (/' Solution and derivative at every second point:',
    + /', ',' x u
99998 FORMAT (' ',F8.3,2F11.5)
99997 FORMAT (//' Tolerance = ',e8.1,' EPS = ',e10.3)
99996 FORMAT (/' Used a mesh of ',I4,' points',/' Maximum error = ',
    + e10.2, in interval ',I4,' for component ',I4)
     END
     SUBROUTINE FFUN(X,Y,NEQ,M,F)
     .. Scalar Arguments ..
     real X
INTEGER NE
                   NEO
     .. Array Arguments ..
     real F(NEQ), Y(NEQ,0:*)
INTEGER M(NEQ)
     .. Scalars in Common ..
    real ALPHA, BETA, EPS
     .. Common blocks ..
                    /PROBS/EPS, ALPHA, BETA
     .. Executable Statements ..
     F(1) = (Y(1,0)-Y(1,0)*Y(1,1))/EPS
     RETURN
     SUBROUTINE FJAC(X,Y,NEQ,M,DF)
     .. Scalar Arguments ..
     real
     INTEGER
                   NEQ
     .. Array Arguments ..
     real DF(NEQ,NEQ,0:*), Y(NEQ,0:*)
                   M(NEQ)
     INTEGER
     .. Scalars in Common ..
     real ALPHA, BETA, EPS
     .. Local Scalars ..
     real FAC, MACHEP, PTRB
     INTEGER I, J, K
     .. Local Arrays ..
```

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```
real
                   F1(1), F2(1), YP(1,0:3)
    .. External Functions ..
                   X02AJF
   real
   EXTERNAL
                   XO2AJF
    .. External Subroutines ...
   EXTERNAL
              FFUN
   .. Intrinsic Functions ..
   INTRINSIC ABS, MAX, SQRT
   .. Common blocks ..
   COMMON /PROBS/EPS, ALPHA, BETA
   .. Executable Statements ..
   MACHEP = XO2AJF()
   FAC = SQRT(MACHEP)
   DO 40 I = 1, NEQ
      DO 20 J = 0, M(I) - 1
         YP(I,J) = Y(I,J)
20
      CONTINUE
40 CONTINUE
   DO 100 I = 1, NEQ
      DO 80 J = 0, M(I) - 1
         PTRB = MAX(1.0e2*MACHEP,FAC*ABS(Y(I,J)))
         YP(I,J) = Y(I,J) + PTRB
         CALL FFUN(X, YP, NEQ, M, F1)
         YP(I,J) = Y(I,J) - PTRB
         CALL FFUN(X, YP, NEQ, M, F2)
         DO 60 K = 1, NEQ
            DF(K,I,J) = 0.5e0*(F1(K)-F2(K))/PTRB
60
         CONTINUE
         YP(I,J) = Y(I,J)
80
      CONTINUE
100 CONTINUE
   RETURN
   END
   SUBROUTINE GAFUN (YA, NEQ, M, NLBC, GA)
    .. Scalar Arguments ..
   INTEGER NEQ, NLBC
   .. Array Arguments ..
             GA(NLBC), YA(NEQ,0:*)
   real
   INTEGER
                   M(NEQ)
   .. Scalars in Common ..
                   ALPHA, BETA, EPS
   .. Common blocks ..
                    /PROBS/EPS, ALPHA, BETA
    .. Executable Statements ..
   GA(1) = YA(1,0) - ALPHA
   RETURN
   SUBROUTINE GBFUN(YB, NEQ, M, NRBC, GB)
   .. Scalar Arguments ..
   INTEGER
                   NEQ, NRBC
   .. Array Arguments ..
                  GB(NRBC), YB(NEQ,0:*)
   INTEGER
                    M(NEQ)
   .. Scalars in Common ..
   real
                   ALPHA, BETA, EPS
   .. Common blocks ..
                   /PROBS/EPS, ALPHA, BETA
    .. Executable Statements ..
```

```
GB(1) = YB(1,0) - BETA
RETURN
END
SUBROUTINE GAJAC(YA, NEQ, M, NLBC, DGA)
.. Parameters ..
           ONE (	ext{ONE=1.0}e + 0)
                ONE
PARAMETER
.. Scalar Arguments ..
INTEGER NEQ, NLBC
.. Array Arguments ..
.. Executable Statements ..
DGA(1,1,0) = ONE
RETURN
END
SUBROUTINE GBJAC(YB, NEQ, M, NRBC, DGB)
.. Parameters ..
real
                ONE
PARAMETER (ONE=1.0e+0)
.. Scalar Arguments ..
INTEGER NEQ, NRBC
.. Array Arguments ..
real DGB(NRBC,NEQ,0:*), YB(NEQ,0:*) INTEGER M(NEQ)
.. Executable Statements ..
DGB(1,1,0) = ONE
RETURN
END
SUBROUTINE GUESS(X, NEQ, M, Z, DMVAL)
.. Scalar Arguments ..
egin{array}{ll} real & {\tt X} \\ {\tt INTEGER} & {\tt NEQ} \end{array}
real
.. Array Arguments ..
.. Scalars in Common ..
real ALPHA, BETA, EPS
.. Common blocks ..
COMMON /PROBS/EPS, ALPHA, BETA
.. Executable Statements ..
Z(1,0) = ALPHA + (BETA-ALPHA)*X
Z(1,1) = (BETA-ALPHA)
DMVAL(1) = 0.0e0
RETURN
END
```

## 9.2 Program Data

None.

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## 9.3 Program Results

DO2TZF Example Program Results

```
Tolerance = 0.1E-04 EPS = 0.100E-03
Used a mesh of 25 points
Maximum error = 0.21E-05 in interval
                                     16 for component
Solution and derivative at every second point:
                      u,
    X
            u
  0.000
          -0.33333
                     1.00000
  0.075
        -0.25833
                     1.00000
  0.150
         -0.18333
                     1.00000
  0.225
          -0.10833
                     1.00002
  0.300
          -0.03332
                     1.00372
  0.400
          -0.00001
                     0.00084
  0.500
          0.00000
                     0.00000
  0.600
          0.00001
                    0.00084
  0.700
          0.03332
                    1.00372
  0.775 0.10833
                   1.00002
  0.850 0.18333
                   1.00000
  0.925 0.25833
                     1.00000
  1.000 0.33333
                     1.00000
Tolerance = 0.1E-04 EPS = 0.100E-04
Used a mesh of
               49 points
Maximum error = 0.21E-05 in interval
                                       32 for component
Solution and derivative at every second point:
            u
          -0.33333
  0.000
                    1.00014
         -0.29583
                   1.00018
  0.038
  0.075
        -0.25833
                   1.00022
  0.113 -0.22083
                   1.00029
  0.150
         -0.18333
                     1.00040
  0.188
         -0.14583
                     1.00059
  0.225
          -0.10833
                     1.00098
  0.262
          -0.07083
                     1.00202
          -0.03333
  0.300
                     1.00745
  0.350
         -0.00001
                     0.00354
  0.400
         0.00000
                     0.00000
  0.450
        0.00000
                     0.00000
  0.500
          0.00000
                     0.00000
  0.550
          0.00000
                     0.00000
  0.600
          0.00000
                     0.00000
  0.650
           0.00001
                     0.00354
  0.700
          0.03333
                     1.00745
  0.737
          0.07083
                     1.00202
  0.775
          0.10833
                     1.00098
  0.813
          0.14583
                     1.00059
  0.850 0.18333
                     1.00040
  0.888
          0.22083
                     1.00029
          0.25833
  0.925
                     1.00022
```

0.963	0.29583	1.00018
1.000	0.33333	1.00014

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