NAG Fortran Library Routine Document F08GUF (CUPMTR/ZUPMTR)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08GUF (CUPMTR/ZUPMTR) multiplies an arbitrary complex matrix C by the complex unitary matrix Q which was determined by F08GSF (CHPTRD/ZHPTRD) when reducing a complex Hermitian matrix to tridiagonal form.

2 Specification

```
SUBROUTINE FO8GUF(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK, INFO)
ENTRY cupmtr (SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK, INFO)
INTEGER M, N, LDC, INFO
complex AP(*), TAU(*), C(LDC,*), WORK(*)
CHARACTER*1 SIDE, UPLO, TRANS
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine is intended to be used after a call to F08GSF (CHPTRD/ZHPTRD), which reduces a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation: $A = QTQ^H$. F08GSF represents the unitary matrix Q as a product of elementary reflectors.

This routine may be used to form one of the matrix products

$$QC$$
, Q^HC , CQ or CQ^H ,

overwriting the result on C (which may be any complex rectangular matrix).

A common application of this routine is to transform a matrix Z of eigenvectors of T to the matrix QZ of eigenvectors of A.

4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

1: SIDE – CHARACTER*1

Input

On entry: indicates how Q or Q^H is to be applied to C as follows:

if SIDE = 'L', Q or Q^H is applied to C from the left;

if SIDE = 'R', Q or Q^H is applied to C from the right.

Constraint: SIDE = 'L' or 'R'.

2: UPLO - CHARACTER*1

Input

On entry: this **must** be the same parameter UPLO as supplied to F08GSF (CHPTRD/ZHPTRD). Constraint: UPLO = 'U' or 'L'.

3: TRANS - CHARACTER*1

Input

On entry: indicates whether Q or Q^H is to be applied to C as follows:

if TRANS = 'N', Q is applied to C;

if TRANS = 'C', Q^H is applied to C.

Constraint: TRANS = 'N' or 'C'.

4: M – INTEGER

Input

On entry: m, the number of rows of the matrix C; m is also the order of Q if SIDE = 'L'. Constraint: M > 0.

5: N – INTEGER

Input

On entry: n, the number of columns of the matrix C; n is also the order of Q if SIDE = 'R'. Constraint: $N \ge 0$.

6: AP(*) - complex array

Input/Output

Note: the dimension of the array AP must be at least max(1, M*(M+1)/2) if SIDE = 'L' and at least max(1, N*(N+1)/2) if SIDE = 'R'.

On entry: details of the vectors which define the elementary reflectors, as returned by F08GSF (CHPTRD/ZHPTRD).

On exit: AP is used as internal workspace prior to being restored and hence is unchanged.

7: TAU(*) - complex array

Input

Note: the dimension of the array TAU must be at least max(1, M-1) if SIDE = 'L' and at least max(1, N-1) if SIDE = 'R'.

On entry: further details of the elementary reflectors, as returned by F08GSF (CHPTRD/ZHPTRD).

8: C(LDC,*) - complex array

Input/Output

Note: the second dimension of the array C must be at least max(1, N).

On entry: the m by n matrix C.

On exit: C is overwritten by QC or Q^HC or CQ or CQ^H as specified by SIDE and TRANS.

9: LDC – INTEGER

Input

On entry: the first dimension of the array C as declared in the (sub)program from which F08GUF (CUPMTR/ZUPMTR) is called.

Constraint: LDC $\geq \max(1, M)$.

10: WORK(*) - complex array

Workspace

Note: the dimension of the array WORK must be at least max(1, N) if SIDE = 'L' and at least max(1, M) if SIDE = 'R'.

11: INFO – INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed result differs from the exact result by a matrix E such that

$$||E||_2 = O(\epsilon)||C||_2$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of real floating-point operations is approximately $8m^2n$ if SIDE = 'L' and $8mn^2$ if SIDE = 'R'.

The real analogue of this routine is F08GGF (SOPMTR/DOPMTR).

9 Example

To compute the two smallest eigenvalues, and the associated eigenvectors, of the matrix A, where

$$A = \begin{pmatrix} -2.28 + 0.00i & 1.78 - 2.03i & 2.26 + 0.10i & -0.12 + 2.53i \\ 1.78 + 2.03i & -1.12 + 0.00i & 0.01 + 0.43i & -1.07 + 0.86i \\ 2.26 - 0.10i & 0.01 - 0.43i & -0.37 + 0.00i & 2.31 - 0.92i \\ -0.12 - 2.53i & -1.07 - 0.86i & 2.31 + 0.92i & -0.73 + 0.00i \end{pmatrix}$$

using packed storage. Here A is Hermitian and must first be reduced to tridiagonal form T by F08GSF (CHPTRD/ZHPTRD). The program then calls F08JJF (SSTEBZ/DSTEBZ) to compute the requested eigenvalues and F08JXF (CSTEIN/ZSTEIN) to compute the associated eigenvectors of T. Finally F08GUF (CUPMTR/ZUPMTR) is called to transform the eigenvectors to those of A.

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO8GUF Example Program Text
Mark 16 Release. NAG Copyright 1992.
.. Parameters ..
                NIN, NOUT
INTEGER
                (NIN=5,NOUT=6)
PARAMETER
INTEGER
                NMAX, LDZ
PARAMETER
                (NMAX=8,LDZ=NMAX)
real
                 ZERO
PARAMETER
                 (ZERO=0.0e0)
.. Local Scalars ..
real
                VL, VU
INTEGER
                I, IFAIL, INFO, J, M, N, NSPLIT
CHARACTER
                UPLO
.. Local Arrays ..
                AP(NMAX*(NMAX+1)/2), TAU(NMAX), WORK(NMAX),
complex
                Z(LDZ,NMAX)
                D(NMAX), E(NMAX), RWORK(5*NMAX), W(NMAX)
real
INTEGER
                 IBLOCK(NMAX), IFAILV(NMAX), ISPLIT(NMAX),
                IWORK(NMAX)
CHARACTER CLABS(1), RLABS(1)
.. External Subroutines ..
```

```
EXTERNAL
                      sstebz, XO4DBF, chptrd, cstein, cupmtr
      .. Executable Statements ..
     WRITE (NOUT,*) 'F08GUF Example Program Results'
     Skip heading in data file
     READ (NIN, *)
     READ (NIN,*) N
     IF (N.LE.NMAX) THEN
        Read A from data file
        READ (NIN, *) UPLO
        IF (UPLO.EQ.'U') THEN
           READ (NIN,*) ((AP(I+J*(J-1)/2),J=I,N),I=1,N)
        ELSE IF (UPLO.EQ.'L') THEN
           READ (NIN,*) ((AP(I+(2*N-J)*(J-1)/2),J=1,I),I=1,N)
        END IF
        Reduce A to tridiagonal form T = (Q**H)*A*Q
        CALL chptrd (UPLO,N,AP,D,E,TAU,INFO)
        Calculate the two smallest eigenvalues of T (same as A)
        CALL sstebz('I','B',N,VL,VU,1,2,ZERO,D,E,M,NSPLIT,W,IBLOCK,
    +
                    ISPLIT,RWORK,IWORK,INFO)
        WRITE (NOUT, *)
        IF (INFO.GT.O) THEN
           WRITE (NOUT,*) 'Failure to converge.'
        ELSE
           WRITE (NOUT, *) 'Eigenvalues'
           WRITE (NOUT, 99999) (W(I), I=1, M)
           Calculate the eigenvectors of T, storing the result in Z
           CALL cstein (N,D,E,M,W,IBLOCK,ISPLIT,Z,LDZ,RWORK,IWORK,
                       IFAILV, INFO)
           IF (INFO.GT.O) THEN
              WRITE (NOUT,*) 'Failure to converge.'
           ELSE
               Calculate the eigenvectors of A = Q * (eigenvectors of T)
               CALL cupmtr('Left', UPLO, 'No transpose', N, M, AP, TAU, Z, LDZ,
                          WORK, INFO)
              Print eigenvectors
              WRITE (NOUT, *)
               IFAIL = 0
               CLABS,80,0,IFAIL)
           END IF
        END IF
     END IF
      STOP
99999 FORMAT (8X,4(F7.4,11X,:))
     END
```

9.2 Program Data

```
FO8GUF Example Program Data

4
'L'
(-2.28, 0.00)
(1.78, 2.03) (-1.12, 0.00)
(2.26,-0.10) (0.01,-0.43) (-0.37, 0.00)
(-0.12,-2.53) (-1.07,-0.86) (2.31, 0.92) (-0.73, 0.00)
:End of matrix A
```

9.3 Program Results