NAG Fortran Library Routine Document F08NSF (CGEHRD/ZGEHRD)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08NSF (CGEHRD/ZGEHRD) reduces a complex general matrix to Hessenberg form.

2 Specification

```
SUBROUTINE FO8NSF(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
ENTRY cgehrd (N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
INTEGER
N, ILO, IHI, LDA, LWORK, INFO
complex
A(LDA,*), TAU(*), WORK(*)
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine reduces a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation: $A = QHQ^H$. H has real subdiagonal elements.

The matrix Q is not formed explicitly, but is represented as a product of elementary reflectors (see the F08 Chapter Introduction for details). Routines are provided to work with Q in this representation (see Section 8).

The routine can take advantage of a previous call to F08NVF (CGEBAL/ZGEBAL), which may produce a matrix with the structure:

$$\begin{pmatrix} A_{11} & A_{12} & A_{13} \\ & A_{22} & A_{23} \\ & & A_{33} \end{pmatrix}$$

where A_{11} and A_{33} are upper triangular. If so, only the central diagonal block A_{22} , in rows and columns i_{lo} to i_{hi} , needs to be reduced to Hessenberg form (the blocks A_{12} and A_{23} will also be affected by the reduction). Therefore the values of i_{lo} and i_{hi} determined by F08NVF (CGEBAL/ZGEBAL) can be supplied to the routine directly. If F08NVF (CGEBAL/ZGEBAL) has not previously been called however, then i_{lo} must be set to 1 and i_{hi} to n.

4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

1: N – INTEGER Input

On entry: n, the order of the matrix A.

Constraint: $N \ge 0$.

ILO – INTEGER
 IHI – INTEGER
 Input

On entry: if A has been output by F08NVF (CGEBAL/ZGEBAL), then ILO and IHI **must** contain the values returned by that routine. Otherwise, ILO must be set to 1 and IHI to N.

Constraints:

$$\label{eq:local_state} \begin{split} 1 & \leq ILO \leq IHI \leq N \text{ if } N > 0, \\ ILO & = 1 \text{ and } IHI = 0 \text{ if } N = 0. \end{split}$$

4: A(LDA,*) - complex array

Input/Output

Note: the second dimension of the array A must be at least max(1, N).

On entry: the n by n general matrix A.

On exit: A is overwritten by the upper Hessenberg matrix H and details of the unitary matrix Q. The subdiagonal elements of H are real.

5: LDA – INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08NSF (CGEHRD/ZGEHRD) is called.

Constraint: LDA $\geq \max(1, N)$.

6: TAU(*) – *complex* array

Output

Note: the dimension of the array TAU must be at least max(1, N - 1).

On exit: further details of the unitary matrix Q.

7: WORK(*) - complex array

Workspace

Note: the dimension of the array WORK must be at least max(1, LWORK).

On exit: if INFO = 0, the real part of WORK(1) contains the minimum value of LWORK required for optimum performance.

8: LWORK – INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08NSF (CGEHRD/ZGEHRD) is called, unless LWORK =-1, in which case a workspace query is assumed and the routine only calculates the optimal dimension of WORK (using the formula given below).

Suggested value: for optimum performance LWORK should be at least $N \times nb$, where nb is the **blocksize**.

Constraint: LWORK $\geq \max(1, N)$ or LWORK = -1.

9: INFO – INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed Hessenberg matrix H is exactly similar to a nearby matrix A + E, where

$$||E||_2 \le c(n)\epsilon ||A||_2,$$

c(n) is a modestly increasing function of n, and ϵ is the machine precision.

The elements of H themselves may be sensitive to small perturbations in A or to rounding errors in the computation, but this does not affect the stability of the eigenvalues, eigenvectors or Schur factorization.

8 Further Comments

The total number of real floating-point operations is approximately $\frac{8}{3}q^2(2q+3n)$, where $q=i_{hi}-i_{lo}$; if $i_{lo}=1$ and $i_{hi}=n$, the number is approximately $\frac{40}{3}n^3$.

To form the unitary matrix Q this routine may be followed by a call to F08NTF (CUNGHR/ZUNGHR):

```
CALL CUNGHR (N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

To apply Q to an m by n complex matrix C this routine may be followed by a call to F08NUF (CUNMHR/ZUNMHR). For example,

```
CALL CUNMHR ('Left','No Transpose',M,N,ILO,IHI,A,LDA,TAU,C,LDC,
WORK,LWORK,INFO)
```

forms the matrix product QC.

The real analogue of this routine is F08NEF (SGEHRD/DGEHRD).

9 Example

To compute the upper Hessenberg form of the matrix A, where

$$A = \begin{pmatrix} -3.97 - 5.04i & -4.11 + 3.70i & -0.34 + 1.01i & 1.29 - 0.86i \\ 0.34 - 1.50i & 1.52 - 0.43i & 1.88 - 5.38i & 3.36 + 0.65i \\ 3.31 - 3.85i & 2.50 + 3.45i & 0.88 - 1.08i & 0.64 - 1.48i \\ -1.10 + 0.82i & 1.81 - 1.59i & 3.25 + 1.33i & 1.57 - 3.44i \end{pmatrix}.$$

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO8NSF Example Program Text
Mark 16 Release. NAG Copyright 1992.
.. Parameters ..
              NIN, NOUT
INTEGER
PARAMETER
                 (NIN=5,NOUT=6)
               NMAX, LDA, LWORK
INTEGER
PARAMETER
                (NMAX=8,LDA=NMAX,LWORK=64*NMAX)
          ZERO
(ZERO=(0.0e0,0.0e0))
complex
PARAMETER
.. Local Scalars ..
INTEGER I, IFAIL, INFO, J, N
.. Local Arrays ..
complex
A(LDA,NMAX), TAU(NMAX-1), WORK(LWORK)
CHARACTER
CLARS(1) PLARS(1)
                CLABS(1), RLABS(1)
CHARACTER
.. External Subroutines ..
EXTERNAL
               XO4DBF, cgehrd
.. Executable Statements ..
WRITE (NOUT,*) 'FO8NSF Example Program Results'
Skip heading in data file
READ (NIN, *)
READ (NIN,*) N
IF (N.LE.NMAX) THEN
   Read A from data file
   READ (NIN, *) ((A(I,J), J=1,N), I=1,N)
   Reduce A to upper Hessenberg form
   CALL cgehrd(N,1,N,A,LDA,TAU,WORK,LWORK,INFO)
```

```
Set the elements below the first sub-diagonal to zero
      DO 40 I = 1, N - 2
         DO 20 J = I + 2, N
           A(J,I) = ZERO
20
         CONTINUE
     CONTINUE
40
     Print upper Hessenberg form
      WRITE (NOUT, *)
      IFAIL = 0
      CALL XO4DBF('General',' ',N,N,A,LDA,'Bracketed','F7.4',
                  'Upper Hessenberg form', 'Integer', RLABS, 'Integer',
                  CLABS,80,0,IFAIL)
  END IF
  STOP
  END
```

9.2 Program Data

```
FO8NSF Example Program Data
4 :Value of N

(-3.97,-5.04) (-4.11, 3.70) (-0.34, 1.01) ( 1.29,-0.86)
( 0.34,-1.50) ( 1.52,-0.43) ( 1.88,-5.38) ( 3.36, 0.65)
( 3.31,-3.85) ( 2.50, 3.45) ( 0.88,-1.08) ( 0.64,-1.48)
(-1.10, 0.82) ( 1.81,-1.59) ( 3.25, 1.33) ( 1.57,-3.44) :End of matrix A
```

9.3 Program Results

FO8NSF Example Program Results

```
Upper Hessenberg form

1 2 3 4

1 (-3.9700,-5.0400) (-1.1318,-2.5693) (-4.6027,-0.1426) (-1.4249, 1.7330)

2 (-5.4797, 0.0000) ( 1.8585,-1.5502) ( 4.4145,-0.7638) (-0.4805,-1.1976)

3 ( 0.0000, 0.0000) ( 6.2673, 0.0000) (-0.4504,-0.0290) (-1.3467, 1.6579)

4 ( 0.0000, 0.0000) ( 0.0000, 0.0000) (-3.5000, 0.0000) ( 2.5619,-3.3708)
```