

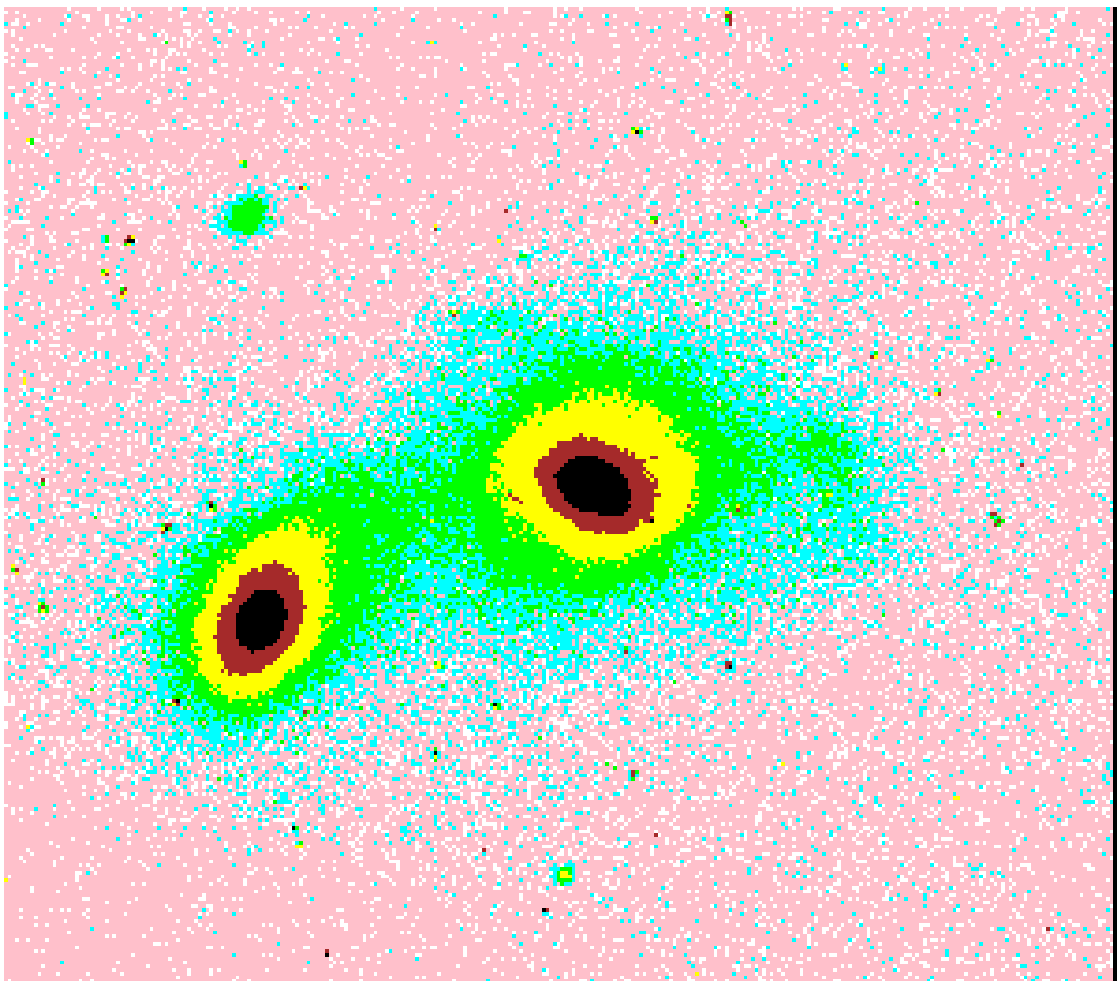
XNICS

Software Maintenance Guide

Version 1.0

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Release notes

Version 1.00

This is a description of software maintenance, including all relevant files and the instruments tuning procedures (from the point of view of supporting software) of the first production version of the **Xnics**, released at 20.07.2000 for the commissioning stage of the **NICS** (Near Infrared Camera-Spectrometer) at **TNG** (Telescopio Nazionale Galileo), La Palma, Spain. The software supports all basic measurement tasks as well as contains the functionality intended for the instruments development and their tuning. The user interface is X11 widget based interface (created upon ATHENA widget set). The software is created as a network distributed software, while basically is executed on the PC dedicated for the measurements.

The manual contains the information necessary for the maintenance of the software file system, including the default contents of all relevant files. The user interface for the instruments tuning is also described.

The information how to use *xnics* in the real measurements one can find in *XNICS. User's Guide*[3]. The other programming details concerning the software are described in *XNICS. Programmer's Guide*[4].

Introduction

This manual describes the structure of the environment — file system organization and the contents of all necessary files — used by the software **Xnics** (**X11 nics**, which was created for the real time control of the measurements using the Arcetri two-dimensional infrared instrument **NICS** (Near Infrared Camera-Spectrometer) [1,2]

The information how to use it in real measurements one can find in *XNICS. User's Guide*[3]. The other programming details concerning the software are described in *XNICS. Programmer's Guide*[4].

The file structure of the Xnics software exists on the PC dedicated for the control of the measuring device (**NICS**) under dedicated account *nics*. The name of the account is irrelevant. Only the file structure is important. The *nics* account is configured to provide the user by Windows95-like screen look-and-feel, using one of the standard Linux window managers, fvwm95. The use of this window manager is arbitrary, but the X11 system running at this account is obligatory. The *xnics* is X11 client and needs for its execution running X11 system, as well as all its shared libraries.

There is some other restricted set of the system elements required by the *xnics*, which will be described in Section 1.6.

For the execution of the *xnics* in the current release, the computer should have two serial ports, connected one with the telescope, another with the motor controller.

Chapter 1

File System of Xnics

The root directory of the software in the root directory of the mentioned account is *xnics*. It contains the sub-directories:

- *bin* with all executable files.
- *data* where the fits files, obtained during the measurements, are stored.
- *jobs* with the job files (the files with the definition of the observation tasks to execute in the **automatic** mode of the measurements during a session.).
- *resource* with the resource files — all the files necessary for the software execution and some templates.
- *src* the root directory of the source files.
- *tmp* the files with necessary system elements, usually not belonging to the standard distributions — fits library and some headers.
- *vbin* files with powerful editor, used for the software development. It is irrelevant for the software execution, but facilitates a lot the files editing.

Only first four directories, *bin*, *data*, *jobs* and *resource* are **obligatory** for the *xnics*.

We describe also the compilation process in the Section 1.6. It could be useful if for some reason the binary modules are lost.

There are also some other directories with the sources or some additional files, but they are related only to software development and maintenance and the user **should never touch them**.

Two files, very relevant to the measurement session, the resource file with a description of a look-and-feel of the user interface widgets, **XNics** as well as the current state snap-shot file, **xnics.ini** are in the account root directory.

It does not matter in reality, where resides the root directory (*nics*) of the *xnics* software and how it is named. Any other name and place can be used, but:

- **the internal structure must be as described above;**
- **the *bin* sub-directory must be included into the account path;**
- **the correct *absolute* path to the software root directory must be included into resource file `XNics` as the values of two resources — `rootDirectory` and `hardwareRootDirectory`;**
- **the correct *absolute* path to the `transnix.btl` binary file (normally in the *bin* sub-directory) must be included into resource file `XNics` as the value of the resource `bootFile`.**

1.1 Binary Files

Two binary modules of *xnics* software, `xnics` and `NICSGate` reside in the *bin* sub-directory. Both these files are copied here during the software compilation. There could be also some old versions of these files.

Two other files, `transnix.btl` and `kernel156.560` contain the binaries of the boot module and DSP kernel, correspondingly, of the software residing in the transputer network. They are booted by *NICSGate* into the transputer network during the initialization phase. The sources of these programs are in *src/transnix* directory and are written in OCCAM. Here we do not touch their creation.

The *xnics* will still work, if these nodules are absent or broken, but all the *transnix* related functionality will not be available.

Two modules `SubtrSky` and `Subtract2` do the subtraction of the sky value from the image and the subtraction of one image from another. These auxiliary programs are called from the *DisplayFrame* menu of *xnics*. Thus their absence or problems with functionality is important for the availability of the corresponding features, but do not influence the main functionality of the *xnics*. These files are copied here during the software compilation. They can be used also from any *xterm* session manually. After making the subtractions they start *SAOimage* viewer to show results. Used without parameters they print the string of their correct usage.

1.2 Data Directory

The main purpose of the *data* directory is for the storage of the files with acquired data. The files created during a given session are saved inside the

sub-directory of the *current* day, created automatically. The “session day” is started at 12:00 instead of 00:00, to cover the session, beginning usually in the evening and finishing in the morning. The subdirectory name consists of two digits for year, two digits for the month and two for the day. Thus the name *000716* means 16 July 2000.

The personal, maintaining the *xnics* software, is responsible to move all the measurements data to other storage devices and to keep enough space on a hard disk for the current measurements.

Xnics creates in a *data* directory two *log* files, one is the session log *xnics.log*, another is the *sensors.log*.

The *xnics* **never** removes them, just updates. **It is the responsibility of the personal, maintaining the *xnics* software, to clean them from time to time.**

1.3 Jobs Directory

The *jobs* directory is intended to contain the *observer*-defined job-files with the observation programs. The only file which should reside here always, is a template file *test.job*. Its absence does not influence the *xnics* functionality at all. But the users should have an example, how to prepare their own jobs correctly.

The files *script1{2,3,4,5}* do the optional part of the observational program. They are intended to contain *any* valid shell script, making necessary auxiliary work projected by an observer. The observer should prepare his/her scripts in advance, check them and copy into the *jobs* directory with one of these **obligatory** names. When the observational program is finished, these scripts should be removed or renamed to permit the others to use this facility.

1.3.1 Jobs Template File

The contents of the jobs template file *test.job* is presented below:

The example of the file with the definition of the observation task.

The file name is *any_name.job*; should be placed in *nics/jobs/* directory.

The lines starting with

space, '.', ';', '#'

are comments and skipped.

The lines started with character different from the mentioned

set when don't have a valid keyword as a first item are popped-up as possible misprintings.

The keywords could have aliases, which are shown below as KEYWORD/ALIAS1/ALIAS2....

The keyword should begin in the FIRST position of the line.

Section description:

valid keywords : job Comment/!

Environment description:

valid keywords : Object/source/object SingleTimeMode
SingleIntTime/tint Coadds/nint
NumberOfGroups/ngroups

valid keywords : ObsMode/obsmode/OBSMODE/mode

valid keywords : Filter/filt Objective/obj Grism/grism Slit/slit
Attenuator/att w12plate/w12/plate

Executable keywords:

valid keywords : SingleFrame/frame SingleGroup/group SeveralGroups
Mosaic/mosaic/MOSAIC Source-Sky/check

Special keyword: System #

can be a single number from 1 to 5

When this item is read the script script# from jobs directory is executed immediately.

Any job section MUST be started by job #
and finished by an executable keyword.

All comments inside this file regard the FOLLOWING lines.

The first job section:

job 1

Comments are valid only for THAT job section where appear.
The number of the comments in the section should be <= 20.

The order of the comments in job section is preserved in fits files header. Thus one can write several lines of the text.
 Comment This text will be added to the fits file header as
 Comment a COMMENT keyword
 ! This too.

The source name to point the telescope on;
 currently pops-up a window with request to the operator and asks
 the confirmation or the break.
 Object test1

The next settings do exactly the same as 'by hands' setting of the
 corresponding items in the main menu
 SingleIntTime 20
 Coadds 2
 NumberOfGroups 1

The parameters of the following keywords should be valid
 items from resources described in resource/work_modes/.
 The incorrect parameters will lead to termination of the task at
 the execution time.
 The only restriction: ObsMode keyword should be presented BEFORE
 any other definition. All definitions PRECEDING the ObsMode
 keyword will be skipped.
 The reason: observation mode definitions are supported INDEPENDENTLY
 for EACH different mode; as a result, when one ObsMode was defined and
 described, the next one could be defined too, and the ACTIVE will be
 the LAST ONE. Obviously, the new definitions for the SAME ObsMode
 replace the previous.
 To choose the already predefined ObsMode as an active it is enough
 to re-declare it again without additional definitions.

ObsMode IMA
 Filter 1mic
 Objective LF

In the next line it is not necessary to write "magnitudes", the valid
 number is enough.
 Attenuator 5 magnitudes

When this or similar keyword is read, the execution of the described
 above job section is started; there still could be some room for
 the interruption and corrections, but very restricted and, obviously,

through the manual mode.
SingleFrame

Sections are executed one-by-one with step=1 incremented number;
if the corresponding section is absent the process will be terminated.
If there are two or more sections with the SAME number, the FIRST one
ONLY is executed.

job 2
! Another comment to finish inside the fits file

The source name to point the telescope on is defined by an alias
keyword;
source test2

Next keyword (only obsmodes.tab is valid as a parameter) declare to
ignore any explicit setting of the Single Integration Time; instead
the default values written in resource/work_modes/obsmodes.tab will
be used
SingleTimeMode obsmodes.tab

Coadds 1
NumberOfGroups 1
ObsMode IMAPOL
Filter 1mic

In the next line it is not necessary to write "degrees", the valid
number is enough.
wl2plate 45 degrees
Source-Sky

Below there are several job sections

job 3
Object test3
SingleIntTime 15
Coadds 2
NumberOfGroups 1

```

ObsMode SPEHR
Grism Jn
  In the next line it is not necessary to write ", the valid
  number is enough.
Slit 0.5"
System 2
Mosaic mosaic0

job 4
Object test4
SingleIntTime 10
Coadds 2
NumberOfGroups 1
ObsMode SPELR
Grism JH
Slit 0.5"
Attenuator 5 magnitudes
Mosaic mosaic1

job 5
Object test5
SingleIntTime 10
Coadds 2
NumberOfGroups 1
ObsMode SPEPOL
Grism Amici
Slit 0.5"
wl2plate 45 degrees
Mosaic mosaic2

```

All following job sections inherit previously defined settings. If everything already have been defined above an should not been changed --- the job section can be reduced till this one:

```

job 6
Mosaic mosaic5

```

This file is self-documented. Additional description one can find in [3].

1.4 Resource Directory

The contents of this directory is very important for the *xnics*. The files residing here are indispensable for the *xnics* functionality.

One of the files, the software resource file is necessary too, but normally resides in the *root* of the *account*. The file here is the default file, which should be copied to normal place if the working file is corrupted.

There are files `instrum.bit`, `motor.bit` and `telescop.bit` with the bitmaps of the instruments statuses.

The files `motors.iniseq` and `sensors.iniseq` contain the sequences of the commands sent to the corresponding devices during the initialization phase.

The list of available *colormaps* for the internal image viewer is stored in the file `colormap.txt`.

The valid *waveform mnemonics*, used for the programming of the transnix waveforms, are written in the file `waveform.mnem`.

There is also the fits file `n526a.b.m.fits` with a dummy image used by the *xnics*.

Below we include the default contents of all necessary files to be restored when corrupted.

There are also the directories, where more resource files reside. These directories collect the resource files united by the common aim — the same device or the task. The description of *mosaic* and *waveforms* directories is included in this section. The files from the motors dedicated directory *work_modes* are included into the next section.

1.4.1 Resource File XNics

The resource file can contain the description of *any* X11 resource. Below we present the contents of this file provided for *xnics* by default.

```
*ObserverLabel.font:  *times-bold-i-*-140-*-*-*-*iso8859-1
*ObserverName.font:  *times-bold-i-*-180-*-*-*-*iso8859-1

*Exit.font:          *helvetica-bold-o-*-180-*-*-*-*iso8859-1

*Command*font:       *courier-bold-r-*-140-*-*-*-*iso8859-1

*IntegrationLabel.font: *courier-bold-o-*-140-*-*-*-*iso8859-1
*FilterLabel.font:     *courier-bold-o-*-140-*-*-*-*iso8859-1
*MosaicLabel.font:     *courier-bold-o-*-140-*-*-*-*iso8859-1

*Command*ListForm.Command.font:  *times-bold-r-*-120-*-*-*-*iso8859-1
*Command*ListField.font:         *courier-bold-r-*-120-*-*-*-*iso8859-1

*font:                *courier-bold-r-*-140-*-*-*-*iso8859-1
```



```
*Temperature.background:    cyan
*Temperature.foreground:    black
*Pressure.background:       cyan
*Pressure.foreground:       black

*statusForm*Command*background: pink
*statusForm*Command*foreground: MidnightBlue

*Exit.background:          cyan
*Setup.background:         PeachPuff
*Exit.foreground:          red

*IntegrationLabel.background: PeachPuff
*IntegrationLabel.foreground: red
*FilterLabel.background:   PeachPuff
*FilterLabel.foreground:   red
*MosaicLabel.background:   PeachPuff
*MosaicLabel.foreground:   red

*Label*background:         MistyRose
*Label*foreground:         DarkGreen
*Text*background:         PaleGreen

*ExitLabel.font:           *helvetica-bold-r-*-140-*-iso8859-1
*ExitLabel.foreground:     MidnightBlue
*ExitForm.background:      red
*ExitForm.foreground:      MidnightBlue
*EXIT.background:         LightBlue
*EXIT.foreground:         red
*CANCEL.background:        green
*CANCEL.foreground:        MidnightBlue

*Command*ListForm.background: green
*Command*ListForm.Dismiss.background: aquamarine
*Command*ListForm.Dismiss.foreground: MidnightBlue
*Command*ListForm.Default.background: gold
*Command*ListForm.Default.foreground: MidnightBlue
*Command*ListField.foreground: MidnightBlue
*Command*ListField.background: PeachPuff

*DisplayFrame*DisplayForm.background: MistyRose
*DisplayFrame*DisplayForm.QUIT.background: green
*DisplayFrame*DisplayForm.QUIT.foreground: Red
```

```
*DisplayFrame*DisplayForm.Label*background: PeachPuff
*DisplayFrame*DisplayForm.Label*foreground: red
*DisplayFrame*DisplayForm*Text*background: PaleGreen
*DisplayFrame*DisplayForm*Text*foreground: black
*DisplayFrame*DisplayForm.Start SAOimage.background: yellow
*DisplayFrame*DisplayForm.Start SAOimage.foreground: MidnightBlue
```

```
*motorstep*background: yellow
*motorstep*foreground: MidnightBlue
```

```
*Setup*background: MistyRose
*Setup.foreground: red
*Setup*Form*QUIT.background: green
*Setup*Form*QUIT.foreground: Red
*Setup*Command*background: aquamarine
*Setup*Command*foreground: MidnightBlue
```

```
*Setup*Command*SetupForm1*background: coral
*Setup*Command*SetupForm1*Label*background: PaleGreen
*Setup*Command*SetupForm1*Label*foreground: MidnightBlue
*Setup*Command*SetupForm1.foreground: red
*Setup*Command*SetupForm1*Command*background: aquamarine
*Setup*Command*SetupForm1*Command*foreground: MidnightBlue
*Setup*Command*SetupForm1*Form.Label*background: PaleGreen
*Setup*Command*SetupForm1*Form.Label*foreground: MidnightBlue
*Setup*Command*SetupForm1*Form.Text*background: Green
*Setup*Command*SetupForm1*Form.Text*foreground: black
```

```
*Command*SetupForm1*background: MistyRose
*Command*SetupForm1.foreground: red
*Command*SetupForm1*Command*background: aquamarine
*Command*SetupForm1*Command*foreground: MidnightBlue
*Command*SetupForm1*Form.Label*background: PaleGreen
*Command*SetupForm1*Form.Label*foreground: MidnightBlue
*Command*SetupForm1*Form.Text*background: Green
*Command*SetupForm1*Form.Text*foreground: black
```

```
*Setup*Command*AcqForm*background: MistyRose
*Setup*Command*AcqForm.foreground: red
*Setup*Command*AcqForm*Command*background: aquamarine
*Setup*Command*AcqForm*Command*foreground: MidnightBlue
*Setup*Command*AcqForm*Form.Label*background: PaleGreen
*Setup*Command*AcqForm*Form.Label*foreground: MidnightBlue
```

```

*Setup*Command*AcqForm*Form.Text*background: Green
*Setup*Command*AcqForm*Form.Text*foreground: black
*Setup*Command*AcqForm*Form.Toggle*background: Green
*Setup*Command*AcqForm*Form.Toggle*foreground: Red

*ObsModes*ObsDevices*background: PaleGreen
*ObsModes*ObsDevices*foreground: black
*ObsModes*ObsDevices*Command*background: Green
*ObsModes*ObsDevices*Command*foreground: red
*ObsModes*ObsDevices*Command*ShadowWidth: 1

*ObsModes*background: cyan
*ObsModes*ImaModes*background: gold
*ObsModes*ImaModes*foreground: MidnightBlue
*ObsModes*SpecModes*background: Yellow
*ObsModes*SpecModes*foreground: MidnightBlue

*ObsModes*ObsDevices*Command*ListForm.background:      white
*ObsModes*ObsDevices*Command*ListForm*Dismiss.background:  green
*ObsModes*ObsDevices*Command*ListForm*Dismiss.foreground:  black
*ObsModes*ObsDevices*Command*ListForm*List1*background:    MistyRose
*ObsModes*ObsDevices*Command*ListForm*List1.foreground:    red
*ObsModes*ObsDevices*Command*ListForm*List2*background:    PeachPuff
*ObsModes*ObsDevices*Command*ListForm*List2.foreground:    MidnightBlue
*ObsModes*ObsDevices*Command*ListForm*List3*background:    magenta
*ObsModes*ObsDevices*Command*ListForm*List3.foreground:    cyan
*ObsModes*ObsDevices*Command*ListForm*List4*background:    PaleGreen
*ObsModes*ObsDevices*Command*ListForm*List4.foreground:    black

*Setup*Command*MotorForm*background:      MistyRose
*Setup*Command*MotorForm.foreground:      red
*Setup*Command*MotorForm*Command*background: aquamarine
*Setup*Command*MotorForm*Command*foreground: MidnightBlue
*Setup*Command*MotorForm*Form.Label*background: PaleGreen
*Setup*Command*MotorForm*Form.Label*foreground: MidnightBlue
*Setup*Command*MotorForm*Form.Text*background: Green
*Setup*Command*MotorForm*Form.Text*foreground: black

*Form*MessageForm*background:      cyan
*Form*MessageForm*foreground:      red
*Form*MessageForm*Command*background: green
*Form*MessageForm*Command*foreground: MidnightBlue
*Form*MessageForm*Command*shadowWidth: 3

```

```

*Command*MessageForm*background:      cyan
*Command*MessageForm*foreground:      red
*Command*MessageForm*Command*background: green
*Command*MessageForm*Command*foreground: MidnightBlue
*Command*MessageForm*Command*shadowWidth: 3

*Label*ShadowWidth: 1
*Scrollbar*ShadowWidth: 0
*ShadowWidth: 5

!for HwInitWidget
*KILL.background:      red
*KILL.foreground:      LightBlue
*DISMISS.background:  green
*DISMISS.foreground:  MidnightBlue
*Clear.background:    yellow
*Clear.foreground:    red
*Scrollbar*background: orange
*Scrollbar*foreground: SpringGreen
*Form*Scrollbar*background: yellow
*Form*Scrollbar*foreground: SpringGreen

*ImageForm*Scrollbar*background:      orange

*ImageForm*Scrollbar*foreground:      SpringGreen
*ImageForm.maxBar.background:        cyan
*ImageForm.maxBar.foreground:        DarkRed
*ImageForm.minBar.background:        DarkRed
*ImageForm.minBar.foreground:        cyan
*ImageForm*intLabel.font: *times-bold-r-*-100-*-*-*-*iso8859-1
*ImageForm*cxLabel.font:  *times-bold-r-*-100-*-*-*-*iso8859-1
*ImageForm*cyLabel.font:  *times-bold-r-*-100-*-*-*-*iso8859-1
*ImageForm*skyLabel.font: *times-bold-r-*-100-*-*-*-*iso8859-1
*ImageForm*spotLabel.font: *times-bold-r-*-100-*-*-*-*iso8859-1
*ImageForm*intLabel.foreground:      red
*ImageForm*intLabel.background:      PeachPuff
*ImageForm*skyLabel.foreground:      red
*ImageForm*skyLabel.background:      PeachPuff

*Command*background:      aquamarine
*Command*foreground:      MidnightBlue

```

```
*Toggle.background:    aquamarine
*Toggle.foreground:    red

*ImageForm.QUIT.background:  green
*ImageForm.QUIT.foreground:  red

*LCForm1.QUIT.background:  green
*LCForm1.QUIT.foreground:  red
*LCForm1.HELP.background:  aquamarine
*LCForm1.HELP.foreground:  red

*test: FALSE
*rootDirectory: /home/nics/nics
*hardwareRootDirectory: /home/nics/nics
*bootFile: /home/nics/nics/bin/transnix.btl

*IntegrationTimeValue:    5.0
*SingleTimeMode: SetByHands

*IntegrationNumberValue:    3
*IntegrationGroupsValue:    1

*singleIntegration:    0

!*biasQ1: 2800
!*biasQ2: 2850
!*biasQ3: 2800
!*biasQ4: 2800
!*biasQ1: 2400
!*biasQ2: 2500
!*biasQ3: 2400
!*biasQ4: 2400
! le tensioni precedenti sono state trovate il 20/5/2000
!*biasQ1: 1
!*biasQ2: 1
!*biasQ3: 1
!*biasQ4: 1
!*polTension1: 1
! le precedenti tensioni servono per il test dell'elettronica
!-----
!*biasQ1: 1670
!*biasQ2: 1610
!*biasQ3: 1630
```

```
!*biasQ4: 1630
!*polTension1: 3000
! le tensioni qui sopra dovrebbero essere quelle usate nel Jan2000 per
! il rivelatore scientifico
!
!*biasQ1: 2850
!*biasQ2: 2800
!*biasQ3: 2300
!*biasQ4: 2300
!*polTension1: 3300
!
! Vlaori sopra trovati con lo scientifico calducco (97K) il 22/5/00,
! Q2 non funzionava, comuqne
!*biasQ1: 2500
!*biasQ2: 3600
!*biasQ3: 2100
!*biasQ4: 2100
!*polTension1: 3300
!
! Vlaori sopra trovati con lo scientifico freddo (75K) il 24/5/00,
! Q2 non funzionava
!*biasQ1: 2450
!*biasQ2: 3600
!*biasQ3: 2150
!*biasQ4: 2120
!*polTension1: 3300
!
! Valori sopra trovati con lo scientifico freddo stabilizzato a 77K
! il 25/5/00, ottimizzati per avere out~=1e4 in signle sampling
! Q2 non funzionava, ricorda che Q1 aveva circuito modificato
!
!
! Valori per multiplexer, 17/7/00 FM & LT
*biasQ1: 2415
*biasQ2: 2110
*biasQ3: 2115
*biasQ4: 2085
*polTension1: 3300

*polTension2: 4000

*sourceX: 520
```

```

*sourceY: 407

*socketBufferSize:    1040
*TimeOutR: 35000
*TelTimeOut: 5
*TelescopeAddress: /dev/ttyS0

*FocusLevel: .5

*BadPixelLevel: 20000
*SaturationLevel: 17000
*SaturationWarning: 257

```

The most part of this file defines look-and-feel of the *xnics*. The internal resources of the *xnics* all have the default values.

Nevertheless, there are the resources, which **must be defined in this resource file**, such as the biases and the polarimeter tensions, because these values were tuned *after* the compilation of the software. The telescope address is obligatory too.

It is also a good rule to set *rootDirectory*, *hardwareRootDirectory* and *bootFile* in *XNics* file.

Some internal settings were also tuned in the resource file after the compilation, such as timeouts, etc. So the best choice is just to use the default file and then add other resources, if necessary.

The complete description of the *xnics/NICSgate* resources is given in [4], while the description in [3] is aimed for the observer.

1.4.2 Bitmaps

There are three bitmap files, containing in ASCII codes the description of the pictures shown in the status buttons. The codification is X11 standard.

The *telescop.bit* file:

```

#define telescop_width 50
#define telescop_height 50
static char telescop_bits[] = {
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0xc0, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0xe0, 0x01, 0x00, 0x00, 0x00, 0x00, 0x00, 0x70, 0x02, 0x00, 0x00, 0x00,
    0x00, 0x00, 0xb8, 0x04, 0x00, 0x00, 0x00, 0x00, 0x00, 0x1c, 0x09, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x4e, 0x12, 0x00, 0x00, 0x00, 0x00, 0x00, 0x26,
    0x34, 0x00, 0x00, 0x00, 0x00, 0x00, 0x03, 0x39, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x81, 0x1c, 0x00, 0x00, 0x00, 0x00, 0x80, 0x02, 0x0e, 0x00, 0x00,

```

```

0x00, 0x00, 0x40, 0x04, 0x07, 0x00, 0x00, 0x00, 0x00, 0x40, 0x89, 0x03,
0x00, 0x00, 0x00, 0x00, 0x60, 0xd0, 0x01, 0x00, 0x00, 0x00, 0x00, 0x30,
0x64, 0x00, 0x00, 0x00, 0x00, 0x00, 0x18, 0x10, 0x00, 0x00, 0x00, 0x00,
0x00, 0x0c, 0x08, 0x00, 0x00, 0x00, 0x00, 0x00, 0x06, 0x07, 0x00, 0x00,
0x00, 0x00, 0x00, 0x81, 0x01, 0x00, 0x00, 0x00, 0x00, 0xc0, 0xc0, 0x00,
0x00, 0x00, 0x00, 0x00, 0x40, 0xe1, 0x00, 0x00, 0x00, 0x00, 0x00, 0x80,
0x62, 0x01, 0x00, 0x00, 0x00, 0x00, 0x40, 0x95, 0x03, 0x00, 0x00, 0x00,
0x00, 0x20, 0xca, 0x06, 0x00, 0x00, 0x00, 0x00, 0x10, 0xcd, 0x06, 0x00,
0x00, 0x00, 0x00, 0x88, 0x80, 0x03, 0x00, 0x00, 0x00, 0x00, 0x46, 0x00,
0x01, 0x00, 0x00, 0x00, 0x00, 0x2a, 0x80, 0x03, 0x00, 0x00, 0x00, 0x00,
0x14, 0xc0, 0x06, 0x00, 0x00, 0x00, 0x00, 0x18, 0x60, 0x0c, 0x00, 0x00,
0x00, 0x00, 0x00, 0x60, 0x0c, 0x00, 0x00, 0x00, 0x00, 0x00, 0x38, 0x38,
0x00, 0x00, 0x00, 0x00, 0x00, 0xf8, 0x3f, 0x00, 0x00, 0x00, 0x00, 0x00,
0xf8, 0x3f, 0x00, 0x00, 0x00, 0x00, 0x00, 0xf8, 0x3f, 0x00, 0x00, 0x00,
0x00, 0x00, 0xf8, 0x3f, 0x00, 0x00, 0x00, 0x00, 0xfe, 0x7f, 0xfc, 0xff,
0x00, 0x00, 0x00, 0x0c, 0x00, 0x00, 0x60, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00};

```

The instrument.bit file:

```

#define instrum_width 50
#define instrum_height 50
static char instrum_bits[] = {
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0xc0, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0xc0, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0xc0, 0x0f, 0x00,
    0x00, 0x00, 0x00, 0x00, 0xc0, 0x7f, 0x00, 0x00, 0x80, 0x00, 0x00, 0x80,
    0xfc, 0x00, 0x00, 0x80, 0x01, 0x00, 0x80, 0xf8, 0x03, 0x00, 0x80, 0x02,
    0x00, 0x80, 0xc8, 0x07, 0x00, 0x80, 0x82, 0x00, 0x80, 0x48, 0x0f, 0x00,
    0x80, 0x82, 0x01, 0x40, 0x44, 0x0f, 0x00, 0x80, 0x82, 0x01, 0x40, 0x44,
    0x0e, 0x00, 0x80, 0x82, 0x03, 0x20, 0x44, 0x0e, 0x00, 0x80, 0x80, 0x02,
    0x20, 0x62, 0x0e, 0x00, 0x80, 0x80, 0x03, 0x20, 0x22, 0x0e, 0x00, 0x80,
    0x80, 0x01, 0x10, 0x22, 0x0e, 0x00, 0x80, 0x80, 0x00, 0x10, 0x22, 0x0e,
    0x00, 0xf0, 0x80, 0x00, 0x10, 0x21, 0x0e, 0x00, 0x90, 0x80, 0x00, 0x10,
    0x31, 0x0e, 0x00, 0x60, 0xe0, 0x00, 0x88, 0x11, 0x0e, 0x00, 0x00, 0xf0,
    0x00, 0x88, 0x10, 0x0e, 0x00, 0x00, 0xf0, 0x00, 0x88, 0x10, 0x0e, 0x00,
    0x00, 0x60, 0x00, 0x84, 0x18, 0x0e, 0x00, 0x00, 0x00, 0x00, 0xc4, 0x08,

```



```

0x0e, 0x00, 0x00, 0x00, 0x00, 0x44, 0x08, 0x0e, 0x00, 0x00, 0x00, 0x00,
0x42, 0x08, 0x07, 0x00, 0x00, 0x00, 0x00, 0x62, 0x0c, 0x07, 0x00, 0x00,
0x00, 0x00, 0x22, 0x04, 0x07, 0x00, 0x00, 0x00, 0x00, 0x31, 0x84, 0x03,
0x00, 0x00, 0x00, 0x00, 0x19, 0xc4, 0x03, 0x00, 0x00, 0x00, 0xc0, 0x09,
0xe4, 0x01, 0x00, 0x00, 0x00, 0xe0, 0xff, 0xff, 0x00, 0x00, 0x00, 0x00,
0xe0, 0xff, 0xff, 0x01, 0x00, 0x00, 0x00, 0xe0, 0xff, 0xff, 0x01, 0x00,
0x00, 0x00, 0xc0, 0xff, 0xff, 0x01, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00};

```

The motor.bit file:

```

#define motor_width 50
#define motor_height 50
static char motor_bits[] = {
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x80, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0xc6,
    0x31, 0x00, 0x00, 0x00, 0x00, 0x00, 0xee, 0x3b, 0x00, 0x00, 0x00, 0x00,
    0x00, 0xff, 0x3f, 0x07, 0x00, 0x00, 0x00, 0xd8, 0xff, 0xff, 0x07, 0x00,
    0x00, 0x00, 0xf8, 0xff, 0xff, 0x07, 0x00, 0x00, 0x00, 0xf0, 0xff, 0xff,
    0x03, 0x00, 0x00, 0x00, 0xf0, 0xff, 0xff, 0x33, 0x00, 0x00, 0x00, 0xff,
    0x3f, 0xfe, 0x3f, 0x00, 0x00, 0x00, 0xff, 0x1f, 0xfc, 0x3f, 0x00, 0x00,
    0x00, 0xfe, 0x1f, 0xfc, 0x1f, 0x00, 0x00, 0x00, 0xfe, 0x18, 0x8c, 0x1f,
    0x00, 0x00, 0x00, 0x7e, 0x30, 0x06, 0x9f, 0x01, 0x00, 0xe0, 0x7f, 0xf0,
    0x07, 0xff, 0x01, 0x00, 0xe0, 0x7f, 0xf0, 0x07, 0xff, 0x00, 0x00, 0x80,
    0xff, 0xf8, 0x8f, 0x7f, 0x00, 0x00, 0x00, 0xff, 0x3f, 0xfe, 0x7f, 0x00,
    0x00, 0x80, 0x8f, 0xdf, 0xfd, 0xf8, 0x00, 0x00, 0xe0, 0x07, 0x2f, 0x7a,
    0xf0, 0x03, 0x00, 0xe0, 0x07, 0x2f, 0x7a, 0xf0, 0x03, 0x00, 0xe0, 0x07,
    0x2f, 0x7a, 0xf0, 0x03, 0x00, 0x80, 0x8f, 0xdf, 0xfd, 0xf8, 0x00, 0x00,
    0x00, 0xff, 0x3f, 0xfe, 0x7f, 0x00, 0x00, 0x80, 0xff, 0xf8, 0x8f, 0xff,
    0x01, 0x00, 0xc0, 0x7f, 0xf0, 0x07, 0xff, 0x01, 0x00, 0xc0, 0x7f, 0xf0,
    0x07, 0xbf, 0x01, 0x00, 0xc0, 0x7e, 0xf0, 0x07, 0x3f, 0x00, 0x00, 0x00,
    0xfe, 0xf8, 0x8f, 0x7f, 0x00, 0x00, 0x00, 0xfc, 0x3f, 0xfe, 0x7f, 0x00,
    0x00, 0x00, 0xfe, 0x1f, 0xfc, 0x7f, 0x00, 0x00, 0x00, 0xfe, 0x1f, 0xfc,
    0x63, 0x00, 0x00, 0x00, 0xe6, 0x1f, 0xfc, 0x07, 0x00, 0x00, 0x00, 0xf0,
    0x3f, 0xfe, 0x0f, 0x00, 0x00, 0x00, 0xf0, 0xff, 0x7f, 0x0e, 0x00, 0x00,
    0x00, 0x70, 0xfe, 0x7f, 0x00, 0x00, 0x00, 0x00, 0x00, 0xfe, 0x7f, 0x00,
    0x00, 0x00, 0x00, 0x00, 0xe7, 0x71, 0x00, 0x00, 0x00, 0x00, 0x00, 0xe3,

```

```

0x01, 0x00, 0x00, 0x00, 0x00, 0x00, 0xc0, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x00};

```

1.4.3 Motors Initial Sequence

The file `motors.iniseq` contains the initial settings for the motors:

```

MN
MR1000
MPA
OSB0
10SC1
20SC1
30SC1
40SC1
50SC1
60SC1
70SC1
70SA0
A1.5
V2
2A0.5
2V0.3
3V1
ST0

```

Each line contains one of the commands to be sent to the motor controller. The available commands are described in [6].

1.4.4 Sensors Initial Sequence

The file `sensors.iniseq` contains the initial setting for the sensors:

```

CUNIK;CUNI?
SUNIK;SUNI?
SCHNB;SCHN?
CCHNA;CCHN?
SETP77;SETP?

```

Some commands useful for the sensors are described in [5].

1.4.5 Colormaps

The file `colormap.txt` contains the list of the available for *xnics* colormaps:

```
gray scale
inverted gray
temperature
black blue red white
gray square root
red scale
green scale
blue scale
yellow scale
magenta scale
aquamarine scale
red-green scale
red-blue scale
green-blue scale
green-red scale
blue-red scale
blue-green scale
16 colors
16 gray
8 gray
4 gray
```

1.4.6 Wave Forms Mnemonics

The file `waveform.mnem` contains the translation table of the mnemonics used in the wave forms files into the numerical values for the NICS revelator:

```
#
#   Tavola di corrispondenza tra gli mnemonici ed i valori
#   numerici dei segnali del rivelatore di nics
#   12/10/98
#
ZERO    0x0000    # per specificare un valore di tutti zeri
PIXEL   0x0001    # un ciclo (0/1/0) avanza di un pixel
XSYNC   0x0002    # normalmente a 1, a 0 inizializza lo SR di riga
LINE    0x0004    # un ciclo (0/1/0) avanza di una riga
YSYNC   0x0008    # normalmente a 1, a 0 inizializza lo SR di colonna
READ    0x0010    # a 1 alimenta i buffer di uscita
RST0    0x0100    # reset quadrante 1
RST1    0x0200    # reset quadrante 2
```

```

RST2    0x0400    # reset quadrante 3
RST3    0x0800    # reset quadrante 4
RSTX    0x0F00    # reset quadranti 1-4
SOC0    0x1000    # inizio conversione quadrante 1
SOC1    0x2000    # inizio conversione quadrante 2
SOC2    0x4000    # inizio conversione quadrante 3
SOC3    0x8000    # inizio conversione quadrante 4
SOCX    0xF000    # inizio conversione quadrante 1-4
DUMMY   0xFF0A    # SOCX + XSYNC + YSYNC

```

1.4.7 Wave Forms Files

Below there are presented the files with the definitions of the **standard** waveforms for NICS revelator. They reside in the subdirectory *waveforms*. There are seven such files.

The file *wf10.inp* :

```

# wf10.inp
#
# Waveform file in symbolic notation
#
# FILE wf10 - Init of frame, from G.Comoretto
#
#
#
# 65290 , 2
# 65282 , 10
# 65290 , 2
# 65288 , 4
# 65290 , 2
#
10                # waveform label
5                 # numero di valori
#
ZERO              , 2      # dummy, no-op value
YSYNC            , 10     # init of          ysync
ZERO              , 2      # dummy, no-op value
XSYNC            , 4      # init of xsync
ZERO              , 2      # dummy, no-op value

```

The file *wf20.inp* :

```

#
# Waveform file in symbolic notation

```

```

#
# FILE wf20 - fast Y shift, from G.Comoretto
#
#
#
# 65294 , 0
# 65290 , 0
#
20                # label
2                 # numero di valori
#
LINE              , 0      # Cshift of Y (line) register
ZERO              , 0      # dummy, no-op value

```

The file wf30.inp :

```

# wf30.inp
#
# Waveform file in symbolic notation
#
# FILE wf30 - initial X shift, from G.Comoretto
#
#
#
# 65304 , 0
# 65304 , 0
# 65304 , 0
# 65304 , 0
# 65304 , 0
# 65304 , 0
# 65306 , 0
# 65306 , 0
# 65306 , 0
# 65306 , 0
# 65307 , 0
# 65307 , 0
# 65307 , 0
# 65307 , 0
# 65307 , 0
# 65306 , 0
#
30                # Waveform label
15                # numero di valori
#
XSYNC + READ     , 0      # init of X (row ) register + read

```

```

XSYNC + READ      , 0      # init of X (row ) register + read
XSYNC + READ      , 0      # init of X (row ) register + read
XSYNC + READ      , 0      # init of X (row ) register + read
XSYNC + READ      , 0      # init of X (row ) register + read
XSYNC + READ      , 0      # init of X (row ) register + read
READ              , 0      # dummy, no-op value + read
READ              , 0      # dummy, no-op value + read
READ              , 0      # dummy, no-op value + read
READ              , 0      # dummy, no-op value + read
READ + PIXEL      , 0      # shift of X (row ) register + read
READ + PIXEL      , 0      # shift of X (row ) register + read
READ + PIXEL      , 0      # shift of X (row ) register + read
READ + PIXEL      , 0      # shift of X (row ) register + read
READ              , 0      # dummy, no-op value + read

```

The file wf40.inp :

```

# wf40.inp
#
# Waveform file in symbolic notation
#
# FILE wf40 - Fast X shift , from G.Comoretto
#
#
#
# 65307 , 2
# 65306 , 0
#
40          # Waveform label
2          # numero di valori
#
READ + PIXEL      , 2      # shift of X (row ) register + read
READ              , 2      # dummy, no-op value + read

```

The file wf50.inp :

```

# wf50.inp
#
# Waveform file in symbolic notation
#
# FILE wf50 - X readout      , from G.Comoretto
#
#
# 65306 , 0

```



```

#
#
60          # Waveform label
3          # numero di elementi (= numero cicli sotto)
#
# In questo caso il valore dopo READ produce un ritardo di valore
# non ancora definito
#
READ          , 2      # dummy, no-op value + read
READ + PIXEL  , 0      # shift of X (row ) register + read
READ          , 0      # dummy, no-op value + read

```

The file wf70.inp :

```

# wf70.inp
#
# Waveform file in symbolic notation
#
# FILE wf70 - X readout clear readout for double correlated sampling
#              (4 us/pixel) , from G.Comoretto
#
#
# 65290 , 0
# 65294 , 0
# 65290 , 0
# 65290 , 0
# 65290 , 0
# 65290 , 0
# 61450 , 0
# 61450 , 0
# 61450 , 0
# 61450 , 0
# 61450 , 0
# 61450 , 0
# 65290 , 0
#
#
70          # Waveform label
13          # numero di valori
#
ZERO          , 0      # dummy, no-op value
LINE          , 0      # dummy, no-op value + Y line
ZERO          , 0      # dummy, no-op value
ZERO          , 0      # dummy, no-op value

```

```

ZERO           , 0      # dummy, no-op value
ZERO           , 0      # dummy, no-op value
RSTX          , 0      # dummy, no-op value + reset
RSTX          , 0      # dummy, no-op value + reset
RSTX          , 0      # dummy, no-op value + reset
RSTX          , 0      # dummy, no-op value + reset
RSTX          , 0      # dummy, no-op value + reset
RSTX          , 0      # dummy, no-op value + reset
RSTX          , 0      # dummy, no-op value + reset
ZERO           , 0      # dummy, no-op value

```

1.4.8 Mosaic Directory

The *mosaic* directory contains the files created by the observers for their observational programs. How create these files is described in [3]. Usually the files should have an extension `.txt`.

Here we represent again the list of the mosaic modes supported by the *xnics* and give a template of such a file.

1. **REL2SOURCE_AD** — the default mode: alpha & delta (right ascension and declination) movements relative to the origin;
2. **REL2LAST_AD** — mode 1: alpha & delta movements relative to the last position;
3. **REL2SOURCE_XY** — mode 2: x & y movements relative to the origin;
4. **REL2LAST_XY** — mode 3: x & y relative to the last position.

The keyword should be placed from the beginning of the line; there can be a comment after it, but the separating space field is obligatory. These keywords may appear in any place of mosaic file changing the subsequent behaviour of the telescope movements elaboration. If there is none of these keywords, the default mosaic mode is assumed.

Below there is an example of such a file:

```

% an example of the mosaic file
% the default movements mode
  0.0  0.0  % posizione "0"
 -35.  35.  % posizione "1"
 110.   0.  % posizione "2"
   0. -110. % posizione "3"
-110.   0.  % posizione "4"
REL2LAST_AD change the movements mode
  0.0  0.0  % posizione "5"

```

```

-35.  35.  % posizione "6"
110.   0.  % posizione "7"
  0. -110. % posizione "8"
-110.   0. % posizione "9"
REL2SOURCE_AD change the movements mode back to default.
  0.0  0.0 % posizione "10"
-45.  45.  % posizione "11"
100.   0.  % posizione "12"
  0. -100. % posizione "13"
-120.   0. % posizione "14"
%
```

1.5 Work Modes Directory

The directory `work_modes` contains the table with the description of all the modes of the observations possible with *xnics*. This table, stored in the file `obsmodes.tab`, is written using the *mnemonics* for the definition of the motors positions. To translate these mnemonics into the number of the steps defining the necessary movement distance of the motor from the home position the files `motor#.pos` are used. Here `#` is the corresponding motor number, from 1 to 7.

There are also the list-menus for all the observation modes, invoked by the corresponding device button in the *parameter panel* of the *xnics* main menu.

All these files are created by Tino Oliva.

1.5.1 Observation Modes Table

The mnemonics from this table should be used in a job file. The `obsmodes.tab` is presented below:

```

#
# Tabellona con tutte le informazioni per i vari modi di osservazione NICS
# Descrizione colonne.
#
# Modes, menus
#
# Motor positions
#   (1) Camera wheel position (name)
#   (2) Array focus position (steps)
#   (3) Lyot stop position (in/out)
#   (4) Filters wheel position (name)
#   (5) Grisms wheel position (name)
```

```

#      (6) Aperture wheel position (name)
#      (7) Aperture sector paddle (name)
#
# DIT:  Suggested DIT
# Will probably add other details of integration setup
#
# Mode, menus                motor_positions                DIT
#                (1)  (2)  (3)  (4)  (5)  (6)  (7)
#-----
# image mode:  IMA filter camera(objective) grey(attenuator)#
#
#
  IMA  dark  LF  G0  LF  any  any  close  any  any  any  30
  IMA  dark  LF  G5  LF  any  any  close  any  any  any  30
  IMA  dark  LF  G10  LF  any  any  close  any  any  any  30
  IMA  dark  SF  G0  SF  any  any  close  any  any  any  30
  IMA  dark  SF  G5  SF  any  any  close  any  any  any  30
  IMA  dark  SF  G10  SF  any  any  close  any  any  any  30
  IMA  1mic  LF  G0  LF  LF1  out  1mic  open  LF  open  30
  IMA  1mic  LF  G5  LF  LF1  out  1mic  grey5  LF  open  30
  IMA  1mic  LF  G10  LF  LF1  out  1mic  grey9  LF  open  30
  IMA  1mic  SF  G0  SF  SF1  out  1mic  open  SF  open  60
  IMA  1mic  SF  G5  SF  SF1  out  1mic  grey5  SF  open  60
  IMA  1mic  SF  G10  SF  SF1  out  1mic  grey9  SF  open  60
  IMA   Jn  LF  G0  LF  LF1  out   Jn  open  LF  open  30
  IMA   Jn  LF  G5  LF  LF1  out   Jn  grey5  LF  open  30
  IMA   Jn  LF  G10  LF  LF1  out   Jn  grey9  LF  open  30
  IMA   Jn  SF  G0  SF  SF1  out   Jn  open  SF  open  60
  IMA   Jn  SF  G5  SF  SF1  out   Jn  grey5  SF  open  60
  IMA   Jn  SF  G10  SF  SF1  out   Jn  grey9  SF  open  60
  IMA   J  LF  G0  LF  LF1  out   J  open  LF  open  30
  IMA   J  LF  G5  LF  LF1  out   J  grey5  LF  open  30
  IMA   J  LF  G10  LF  LF1  out   J  grey9  LF  open  30
  IMA   J  SF  G0  SF  SF1  out   J  open  SF  open  60
  IMA   J  SF  G5  SF  SF1  out   J  grey5  SF  open  60
  IMA   J  SF  G10  SF  SF1  out   J  grey9  SF  open  60
  IMA   H  LF  G0  LF  LF1  out   H  open  LF  open  20
  IMA   H  LF  G5  LF  LF1  out   H  grey5  LF  open  20
  IMA   H  LF  G10  LF  LF1  out   H  grey9  LF  open  20
  IMA   H  SF  G0  SF  SF1  out   H  open  SF  open  40
  IMA   H  SF  G5  SF  SF1  out   H  grey5  SF  open  40
  IMA   H  SF  G10  SF  SF1  out   H  grey9  SF  open  40
  IMA   K'  LF  G0  LF  LF1  out   K'  open  LF  open  20

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	IMA	K'	LF	G5	LF	LF1	out	K'	grey5	LF	open	20
	IMA	K'	LF	G10	LF	LF1	out	K'	grey9	LF	open	20
	IMA	K'	SF	G0	SF	SF1	out	K'	open	SF	open	40
	IMA	K'	SF	G5	SF	SF1	out	K'	grey5	SF	open	40
	IMA	K'	SF	G10	SF	SF1	out	K'	grey9	SF	open	40
#	IMA	K	LF	G0	LF	LF1	out	K	open	LF	open	20
	IMA	K	LF	G0	LF	LF1	out	Kflat	open	LF	open	20
	IMA	K	LF	G5	LF	LF1	out	K	grey5	LF	open	20
	IMA	K	LF	G10	LF	LF1	out	K	grey9	LF	open	20
	IMA	K	SF	G0	SF	SF1	out	K	open	SF	open	40
	IMA	K	SF	G5	SF	SF1	out	K	grey5	SF	open	40
	IMA	K	SF	G10	SF	SF1	out	K	grey9	SF	open	40
	IMA	HK'	LF	G0	LF	LF1	out	HK'	open	LF	open	20
	IMA	HK'	LF	G5	LF	LF1	out	HK'	grey5	LF	open	20
	IMA	HK'	LF	G10	LF	LF1	out	HK'	grey9	LF	open	20
	IMA	HK'	SF	G0	SF	SF1	out	HK'	open	SF	open	40
	IMA	HK'	SF	G5	SF	SF1	out	HK'	grey5	SF	open	40
	IMA	HK'	SF	G10	SF	SF1	out	HK'	grey9	SF	open	40
	IMA	SW	LF	G0	LF	LF1	out	open	SW	LF	open	20
	IMA	SW	LF	G5	LF	LF1	out	grey5	SW	LF	open	20
	IMA	SW	LF	G10	LF	LF1	out	grey9	SW	LF	open	20
	IMA	SW	SF	G0	SF	SF1	out	open	SW	SF	open	40
	IMA	SW	SF	G5	SF	SF1	out	grey5	SW	SF	open	40
	IMA	SW	SF	G10	SF	SF1	out	grey9	SW	SF	open	40
	IMA	Zn	LF	G0	LF	LF1	out	Zn	open	LF	open	30
	IMA	Zn	LF	G5	LF	LF1	out	Zn	grey5	LF	open	30
	IMA	Zn	LF	G10	LF	LF1	out	Zn	grey9	LF	open	30
	IMA	Zn	SF	G0	SF	SF1	out	Zn	open	SF	open	60
	IMA	Zn	SF	G5	SF	SF1	out	Zn	grey5	SF	open	60
	IMA	Zn	SF	G10	SF	SF1	out	Zn	grey9	SF	open	60
	IMA	Brg	LF	G0	LF	LF1	out	Brg	open	LF	open	60
	IMA	Brg	LF	G5	LF	LF1	out	Brg	grey5	LF	open	60
	IMA	Brg	LF	G10	LF	LF1	out	Brg	grey9	LF	open	60
	IMA	Brg	SF	G0	SF	SF1	out	Brg	open	SF	open	60
	IMA	Brg	SF	G5	SF	SF1	out	Brg	grey5	SF	open	60
	IMA	Brg	SF	G10	SF	SF1	out	Brg	grey9	SF	open	60
	IMA	H2	LF	G0	LF	LF1	out	H2	open	LF	open	60
	IMA	H2	LF	G5	LF	LF1	out	H2	grey5	LF	open	60
	IMA	H2	LF	G10	LF	LF1	out	H2	grey9	LF	open	60
	IMA	H2	SF	G0	SF	SF1	out	H2	open	SF	open	60
	IMA	H2	SF	G5	SF	SF1	out	H2	grey5	SF	open	60
	IMA	H2	SF	G10	SF	SF1	out	H2	grey9	SF	open	60
	IMA	FeII	LF	G0	LF	LF1	out	FeII	open	LF	open	60

IMA	FeII	LF	G5	LF	LF1	out	FeII	grey5	LF	open	60	
IMA	FeII	LF	G10	LF	LF1	out	FeII	grey9	LF	open	60	
IMA	FeII	SF	G0	SF	SF1	out	FeII	open	SF	open	60	
IMA	FeII	SF	G5	SF	SF1	out	FeII	grey5	SF	open	60	
IMA	FeII	SF	G10	SF	SF1	out	FeII	grey9	SF	open	60	
IMA	Kcont	LF	G0	LF	LF1	out	Kcont	open	LF	open	60	
IMA	Kcont	LF	G5	LF	LF1	out	Kcont	grey5	LF	open	60	
IMA	Kcont	LF	G10	LF	LF1	out	Kcont	grey9	LF	open	60	
IMA	Kcont	SF	G0	SF	SF1	out	Kcont	open	SF	open	60	
IMA	Kcont	SF	G5	SF	SF1	out	Kcont	grey5	SF	open	60	
IMA	Kcont	SF	G10	SF	SF1	out	Kcont	grey9	SF	open	60	
IMA	Hcont	LF	G0	LF	LF1	out	Hcont	open	LF	open	60	
IMA	Hcont	LF	G5	LF	LF1	out	Hcont	grey5	LF	open	60	
IMA	Hcont	LF	G10	LF	LF1	out	Hcont	grey9	LF	open	60	
IMA	Hcont	SF	G0	SF	SF1	out	Hcont	open	SF	open	60	
IMA	Hcont	SF	G5	SF	SF1	out	Hcont	grey5	SF	open	60	
IMA	Hcont	SF	G10	SF	SF1	out	Hcont	grey9	SF	open	60	
#												
#	# Note that grey filters cannot be used with Ks setup											
#												
	IMA	Ks	LF	G0	LF	LF1	out	K	K'	LF	open	20
	IMA	Ks	SF	G0	SF	SF1	out	K	K'	SF	open	40
#												
#	-----											
#	# imaging polarimetry mode: IMAPOL filter plate_ange											
#												
IMAPOL	dark	P0		LF	any	any	close	any	any	any		60
IMAPOL	dark	P45		LF	any	any	close	any	any	any		60
IMAPOL	1mic	P0		LF	LF1	out	1mic	Woll	SF	P0		30
IMAPOL	1mic	P45		LF	LF1	out	1mic	Woll	SF	P45		30
IMAPOL	Jn	P0		LF	LF1	out	Jn	Woll	SF	P0		30
IMAPOL	Jn	P45		LF	LF1	out	Jn	Woll	SF	P45		30
IMAPOL	J	P0		LF	LF1	out	J	Woll	SF	P0		30
IMAPOL	J	P45		LF	LF1	out	J	Woll	SF	P45		30
IMAPOL	H	P0		LF	LF1	out	H	Woll	SF	P0		30
IMAPOL	H	P45		LF	LF1	out	H	Woll	SF	P45		30
IMAPOL	K'	P0		LF	LF1	out	K'	Woll	SF	P0		30
IMAPOL	K'	P45		LF	LF1	out	K'	Woll	SF	P45		30
IMAPOL	K	P0		LF	LF1	out	K	Woll	SF	P0		30
IMAPOL	K	P45		LF	LF1	out	K	Woll	SF	P45		30
IMAPOL	HK'	P0		LF	LF1	out	HK'	Woll	SF	P0		30
IMAPOL	HK'	P45		LF	LF1	out	HK'	Woll	SF	P45		30
IMAPOL	Zn	P0		LF	LF1	out	Zn	Woll	SF	P0		30

IMAPOL	Zn	P45	LF	LF1	out	Zn	Woll	SF	P45	30
IMAPOL	Brg	P0	LF	LF1	out	Brg	Woll	SF	P0	30
IMAPOL	Brg	P45	LF	LF1	out	Brg	Woll	SF	P45	30
IMAPOL	H2	P0	LF	LF1	out	H2	Woll	SF	P0	30
IMAPOL	H2	P45	LF	LF1	out	H2	Woll	SF	P45	30
IMAPOL	FeII	P0	LF	LF1	out	FeII	Woll	SF	P0	30
IMAPOL	FeII	P45	LF	LF1	out	FeII	Woll	SF	P45	30
IMAPOL	Kcont	P0	LF	LF1	out	Kcont	Woll	SF	P0	30
IMAPOL	Kcont	P45	LF	LF1	out	Kcont	Woll	SF	P45	30
IMAPOL	Hcont	P0	LF	LF1	out	Hcont	Woll	SF	P0	30
IMAPOL	Hcont	P45	LF	LF1	out	Hcont	Woll	SF	P45	30

#

#-----

low resolution spectroscopy: SPELR grism slit grey(attenuator)#

NB: grism=view# means using a certain filter to look at the slit

and check if object is centered. Only SW and K

filters are foreseen at the moment

#

slit=none means slitless (could be useful to determine efficiency)

#

SPELR	dark	0.5	G0	LF	any	any	close	any	any	any	60
SPELR	dark	0.5	G5	LF	any	any	close	any	any	any	60
SPELR	dark	0.5	G10	LF	any	any	close	any	any	any	60
SPELR	dark	0.75	G0	LF	any	any	close	any	any	any	60
SPELR	dark	0.75	G5	LF	any	any	close	any	any	any	60
SPELR	dark	0.75	G10	LF	any	any	close	any	any	any	60
SPELR	dark	1.0	G0	LF	any	any	close	any	any	any	60
SPELR	dark	1.0	G5	LF	any	any	close	any	any	any	60
SPELR	dark	1.0	G10	LF	any	any	close	any	any	any	60
SPELR	dark	1.5	G0	LF	any	any	close	any	any	any	60
SPELR	dark	1.5	G5	LF	any	any	close	any	any	any	60
SPELR	dark	1.5	G10	LF	any	any	close	any	any	any	60
SPELR	dark	2.0	G0	LF	any	any	close	any	any	any	60
SPELR	dark	2.0	G5	LF	any	any	close	any	any	any	60
SPELR	dark	2.0	G10	LF	any	any	close	any	any	any	60
SPELR	dark	none	G0	LF	any	any	close	any	any	any	60
SPELR	dark	none	G5	LF	any	any	close	any	any	any	60
SPELR	dark	none	G10	LF	any	any	close	any	any	any	60
SPELR	AMICI	0.5	G0	LF	LF1	out	open	Amici	0.5	open	60
SPELR	AMICI	0.5	G5	LF	LF1	out	grey5	Amici	0.5	open	60
SPELR	AMICI	0.5	G10	LF	LF1	out	grey9	Amici	0.5	open	60
SPELR	AMICI	0.75	G0	LF	LF1	out	open	Amici	0.75	open	60
SPELR	AMICI	0.75	G5	LF	LF1	out	grey5	Amici	0.75	open	60

SPELR	AMICI	0.75	G10	LF	LF1	out	grey9	Amici	0.75	open	60
SPELR	AMICI	1.0	G0	LF	LF1	out	open	Amici	1.0	open	60
SPELR	AMICI	1.0	G5	LF	LF1	out	grey5	Amici	1.0	open	60
SPELR	AMICI	1.0	G10	LF	LF1	out	grey9	Amici	1.0	open	60
SPELR	AMICI	1.5	G0	LF	LF1	out	open	Amici	1.5	open	60
SPELR	AMICI	1.5	G5	LF	LF1	out	grey5	Amici	1.5	open	60
SPELR	AMICI	1.5	G10	LF	LF1	out	grey9	Amici	1.5	open	60
SPELR	AMICI	2.0	G0	LF	LF1	out	open	Amici	2.0	open	60
SPELR	AMICI	2.0	G5	LF	LF1	out	grey5	Amici	2.0	open	60
SPELR	AMICI	2.0	G10	LF	LF1	out	grey9	Amici	2.0	open	60
SPELR	AMICI	none	G0	LF	LF1	out	open	Amici	LF	open	60
SPELR	AMICI	none	G5	LF	LF1	out	grey5	Amici	LF	open	60
SPELR	AMICI	none	G10	LF	LF1	out	grey9	Amici	LF	open	60
SPELR	IJ	0.5	G0	LF	LF1	out	open	IJ	0.5	open	60
SPELR	IJ	0.5	G5	LF	LF1	out	grey5	IJ	0.5	open	60
SPELR	IJ	0.5	G10	LF	LF1	out	grey9	IJ	0.5	open	60
SPELR	IJ	0.75	G0	LF	LF1	out	open	IJ	0.75	open	60
SPELR	IJ	0.75	G5	LF	LF1	out	grey5	IJ	0.75	open	60
SPELR	IJ	0.75	G10	LF	LF1	out	grey9	IJ	0.75	open	60
SPELR	IJ	1.0	G0	LF	LF1	out	open	IJ	1.0	open	60
SPELR	IJ	1.0	G5	LF	LF1	out	grey5	IJ	1.0	open	60
SPELR	IJ	1.0	G10	LF	LF1	out	grey9	IJ	1.0	open	60
SPELR	IJ	1.5	G0	LF	LF1	out	open	IJ	1.5	open	60
SPELR	IJ	1.5	G5	LF	LF1	out	grey5	IJ	1.5	open	60
SPELR	IJ	1.5	G10	LF	LF1	out	grey9	IJ	1.5	open	60
SPELR	IJ	2.0	G0	LF	LF1	out	open	IJ	2.0	open	60
SPELR	IJ	2.0	G5	LF	LF1	out	grey5	IJ	2.0	open	60
SPELR	IJ	2.0	G10	LF	LF1	out	grey9	IJ	2.0	open	60
SPELR	IJ	none	G0	LF	LF1	out	open	IJ	LF	open	60
SPELR	IJ	none	G5	LF	LF1	out	grey5	IJ	LF	open	60
SPELR	IJ	none	G10	LF	LF1	out	grey9	IJ	LF	open	60
SPELR	JH	0.5	G0	LF	LF1	out	open	JH	0.5	open	60
SPELR	JH	0.5	G5	LF	LF1	out	grey5	JH	0.5	open	60
SPELR	JH	0.5	G10	LF	LF1	out	grey9	JH	0.5	open	60
SPELR	JH	0.75	G0	LF	LF1	out	open	JH	0.75	open	60
SPELR	JH	0.75	G5	LF	LF1	out	grey5	JH	0.75	open	60
SPELR	JH	0.75	G10	LF	LF1	out	grey9	JH	0.75	open	60
SPELR	JH	1.0	G0	LF	LF1	out	open	JH	1.0	open	60
SPELR	JH	1.0	G5	LF	LF1	out	grey5	JH	1.0	open	60
SPELR	JH	1.0	G10	LF	LF1	out	grey9	JH	1.0	open	60
SPELR	JH	1.5	G0	LF	LF1	out	open	JH	1.5	open	60
SPELR	JH	1.5	G5	LF	LF1	out	grey5	JH	1.5	open	60
SPELR	JH	1.5	G10	LF	LF1	out	grey9	JH	1.5	open	60

SPELR	JH	2.0	G0	LF	LF1	out	open	JH	2.0	open	60
SPELR	JH	2.0	G5	LF	LF1	out	grey5	JH	2.0	open	60
SPELR	JH	2.0	G10	LF	LF1	out	grey9	JH	2.0	open	60
SPELR	JH	none	G0	LF	LF1	out	open	JH	LF	open	60
SPELR	JH	none	G5	LF	LF1	out	grey5	JH	LF	open	60
SPELR	JH	none	G10	LF	LF1	out	grey9	JH	LF	open	60
SPELR	JK'	0.5	G0	LF	LF1	out	open	JK'	0.5	open	60
SPELR	JK'	0.5	G5	LF	LF1	out	grey5	JK'	0.5	open	60
SPELR	JK'	0.5	G10	LF	LF1	out	grey9	JK'	0.5	open	60
SPELR	JK'	0.75	G0	LF	LF1	out	open	JK'	0.75	open	60
SPELR	JK'	0.75	G5	LF	LF1	out	grey5	JK'	0.75	open	60
SPELR	JK'	0.75	G10	LF	LF1	out	grey9	JK'	0.75	open	60
SPELR	JK'	1.0	G0	LF	LF1	out	open	JK'	1.0	open	60
SPELR	JK'	1.0	G5	LF	LF1	out	grey5	JK'	1.0	open	60
SPELR	JK'	1.0	G10	LF	LF1	out	grey9	JK'	1.0	open	60
SPELR	JK'	1.5	G0	LF	LF1	out	open	JK'	1.5	open	60
SPELR	JK'	1.5	G5	LF	LF1	out	grey5	JK'	1.5	open	60
SPELR	JK'	1.5	G10	LF	LF1	out	grey9	JK'	1.5	open	60
SPELR	JK'	2.0	G0	LF	LF1	out	open	JK'	2.0	open	60
SPELR	JK'	2.0	G5	LF	LF1	out	grey5	JK'	2.0	open	60
SPELR	JK'	2.0	G10	LF	LF1	out	grey9	JK'	2.0	open	60
SPELR	JK'	none	G0	LF	LF1	out	open	JK'	LF	open	60
SPELR	JK'	none	G5	LF	LF1	out	grey5	JK'	LF	open	60
SPELR	JK'	none	G10	LF	LF1	out	grey9	JK'	LF	open	60
SPELR	HK	0.5	G0	LF	LF1	out	open	HK	0.5	open	60
SPELR	HK	0.5	G5	LF	LF1	out	grey5	HK	0.5	open	60
SPELR	HK	0.5	G10	LF	LF1	out	grey9	HK	0.5	open	60
SPELR	HK	0.75	G0	LF	LF1	out	open	HK	0.75	open	60
SPELR	HK	0.75	G5	LF	LF1	out	grey5	HK	0.75	open	60
SPELR	HK	0.75	G10	LF	LF1	out	grey9	HK	0.75	open	60
SPELR	HK	1.0	G0	LF	LF1	out	open	HK	1.0	open	60
SPELR	HK	1.0	G5	LF	LF1	out	grey5	HK	1.0	open	60
SPELR	HK	1.0	G10	LF	LF1	out	grey9	HK	1.0	open	60
SPELR	HK	1.5	G0	LF	LF1	out	open	HK	1.5	open	60
SPELR	HK	1.5	G5	LF	LF1	out	grey5	HK	1.5	open	60
SPELR	HK	1.5	G10	LF	LF1	out	grey9	HK	1.5	open	60
SPELR	HK	2.0	G0	LF	LF1	out	open	HK	2.0	open	60
SPELR	HK	2.0	G5	LF	LF1	out	grey5	HK	2.0	open	60
SPELR	HK	2.0	G10	LF	LF1	out	grey9	HK	2.0	open	60
SPELR	HK	none	G0	LF	LF1	out	open	HK	LF	open	60
SPELR	HK	none	G5	LF	LF1	out	grey5	HK	LF	open	60
SPELR	HK	none	G10	LF	LF1	out	grey9	HK	LF	open	60
SPELR	viewS	0.5	G0	LF	LF1	out	open	SW	0.5	open	20

SPELR viewS	0.5	G5	LF	LF1	out	grey5	SW	0.5	open	20	
SPELR viewS	0.5	G10	LF	LF1	out	grey9	SW	0.5	open	20	
SPELR viewS	0.75	G0	LF	LF1	out	open	SW	0.75	open	20	
SPELR viewS	0.75	G5	LF	LF1	out	grey5	SW	0.75	open	20	
SPELR viewS	0.75	G10	LF	LF1	out	grey9	SW	0.75	open	20	
SPELR viewS	1.0	G0	LF	LF1	out	open	SW	1.0	open	20	
SPELR viewS	1.0	G5	LF	LF1	out	grey5	SW	1.0	open	20	
SPELR viewS	1.0	G10	LF	LF1	out	grey9	SW	1.0	open	20	
SPELR viewS	1.5	G0	LF	LF1	out	open	SW	1.5	open	20	
SPELR viewS	1.5	G5	LF	LF1	out	grey5	SW	1.5	open	20	
SPELR viewS	1.5	G10	LF	LF1	out	grey9	SW	1.5	open	20	
SPELR viewS	2.0	G0	LF	LF1	out	open	SW	2.0	open	20	
SPELR viewS	2.0	G5	LF	LF1	out	grey5	SW	2.0	open	20	
SPELR viewS	2.0	G10	LF	LF1	out	grey9	SW	2.0	open	20	
SPELR viewS	none	G0	LF	LF1	out	open	SW	LF	open	20	
SPELR viewS	none	G5	LF	LF1	out	grey5	SW	LF	open	20	
SPELR viewS	none	G10	LF	LF1	out	grey9	SW	LF	open	20	
SPELR viewK	0.5	G0	LF	LF1	out	K	open	0.5	open	15	
SPELR viewK	0.5	G5	LF	LF1	out	K	grey5	0.5	open	15	
SPELR viewK	0.5	G10	LF	LF1	out	K	grey9	0.5	open	15	
SPELR viewK	0.75	G0	LF	LF1	out	K	open	0.75	open	15	
SPELR viewK	0.75	G5	LF	LF1	out	K	grey5	0.75	open	15	
SPELR viewK	0.75	G10	LF	LF1	out	K	grey9	0.75	open	15	
SPELR viewK	1.0	G0	LF	LF1	out	K	open	1.0	open	15	
SPELR viewK	1.0	G5	LF	LF1	out	K	grey5	1.0	open	15	
SPELR viewK	1.0	G10	LF	LF1	out	K	grey9	1.0	open	15	
SPELR viewK	1.5	G0	LF	LF1	out	K	open	1.5	open	15	
SPELR viewK	1.5	G5	LF	LF1	out	K	grey5	1.5	open	15	
SPELR viewK	1.5	G10	LF	LF1	out	K	grey9	1.5	open	15	
SPELR viewK	2.0	G0	LF	LF1	out	K	open	2.0	open	15	
SPELR viewK	2.0	G5	LF	LF1	out	K	grey5	2.0	open	15	
SPELR viewK	2.0	G10	LF	LF1	out	K	grey9	2.0	open	15	
SPELR viewK	none	G0	LF	LF1	out	K	open	LF	open	15	
SPELR viewK	none	G5	LF	LF1	out	K	grey5	LF	open	15	
SPELR viewK	none	G10	LF	LF1	out	K	grey9	LF	open	15	
#											
#	-----										
#	spectro-polarimetry: SPEPOL grism slit plate_angle(P0-P45)										
#											
SPEPOL	dark	0.5	P0	LF	any	any	close	any	any	any	60
SPEPOL	dark	0.5	G5	LF	any	any	close	any	any	any	60
SPEPOL	dark	0.75	P0	LF	any	any	close	any	any	any	60
SPEPOL	dark	0.75	P45	LF	any	any	close	any	any	any	60

SPEPOL	dark	1.0	P0	LF	any	any	close	any	any	any	60
SPEPOL	dark	1.0	P45	LF	any	any	close	any	any	any	60
SPEPOL	dark	1.5	P0	LF	any	any	close	any	any	any	60
SPEPOL	dark	1.5	P45	LF	any	any	close	any	any	any	60
SPEPOL	dark	2.0	P0	LF	any	any	close	any	any	any	60
SPEPOL	dark	2.0	P45	LF	any	any	close	any	any	any	60
SPEPOL	dark	none	P0	LF	any	any	close	any	any	any	60
SPEPOL	dark	none	P45	LF	any	any	close	any	any	any	60
SPEPOL	AMICI	0.5	P0	LF	LF1	out	Woll	Amici	0.5	P0	60
SPEPOL	AMICI	0.5	P45	LF	LF1	out	Woll	Amici	0.5	P45	60
SPEPOL	AMICI	0.75	P0	LF	LF1	out	Woll	Amici	0.75	P0	60
SPEPOL	AMICI	0.75	P45	LF	LF1	out	Woll	Amici	0.75	P45	60
SPEPOL	AMICI	1.0	P0	LF	LF1	out	Woll	Amici	1.0	P0	60
SPEPOL	AMICI	1.0	P45	LF	LF1	out	Woll	Amici	1.0	P45	60
SPEPOL	AMICI	1.5	P0	LF	LF1	out	Woll	Amici	1.5	P0	60
SPEPOL	AMICI	1.5	P45	LF	LF1	out	Woll	Amici	1.5	P45	60
SPEPOL	AMICI	2.0	P0	LF	LF1	out	Woll	Amici	2.0	P0	60
SPEPOL	AMICI	2.0	P45	LF	LF1	out	Woll	Amici	2.0	P45	60
SPEPOL	AMICI	none	P0	LF	LF1	out	Woll	Amici	SF	P0	60
SPEPOL	AMICI	none	P45	LF	LF1	out	Woll	Amici	SF	P45	60
SPEPOL	IJ	0.5	P0	LF	LF1	out	Woll	IJ	0.5	P0	60
SPEPOL	IJ	0.5	P45	LF	LF1	out	Woll	IJ	0.5	P45	60
SPEPOL	IJ	0.75	P0	LF	LF1	out	Woll	IJ	0.75	P0	60
SPEPOL	IJ	0.75	P45	LF	LF1	out	Woll	IJ	0.75	P45	60
SPEPOL	IJ	1.0	P0	LF	LF1	out	Woll	IJ	1.0	P0	60
SPEPOL	IJ	1.0	P45	LF	LF1	out	Woll	IJ	1.0	P45	60
SPEPOL	IJ	1.5	P0	LF	LF1	out	Woll	IJ	1.5	P0	60
SPEPOL	IJ	1.5	P45	LF	LF1	out	Woll	IJ	1.5	P45	60
SPEPOL	IJ	2.0	P0	LF	LF1	out	Woll	IJ	2.0	P0	60
SPEPOL	IJ	2.0	P45	LF	LF1	out	Woll	IJ	2.0	P45	60
SPEPOL	IJ	none	P0	LF	LF1	out	Woll	IJ	SF	P0	60
SPEPOL	IJ	none	P45	LF	LF1	out	Woll	IJ	SF	P45	60
SPEPOL	JH	0.5	P0	LF	LF1	out	Woll	JH	0.5	P0	60
SPEPOL	JH	0.5	P45	LF	LF1	out	Woll	JH	0.5	P45	60
SPEPOL	JH	0.75	P0	LF	LF1	out	Woll	JH	0.75	P0	60
SPEPOL	JH	0.75	P45	LF	LF1	out	Woll	JH	0.75	P45	60
SPEPOL	JH	1.0	P0	LF	LF1	out	Woll	JH	1.0	P0	60
SPEPOL	JH	1.0	P45	LF	LF1	out	Woll	JH	1.0	P45	60
SPEPOL	JH	1.5	P0	LF	LF1	out	Woll	JH	1.5	P0	60
SPEPOL	JH	1.5	P45	LF	LF1	out	Woll	JH	1.5	P45	60
SPEPOL	JH	2.0	P0	LF	LF1	out	Woll	JH	2.0	P0	60
SPEPOL	JH	2.0	P45	LF	LF1	out	Woll	JH	2.0	P45	60
SPEPOL	JH	none	P0	LF	LF1	out	Woll	JH	SF	P0	60

SPEPOL	JH	none	P45	LF	LF1	out	Woll	JH	SF	P45	60
SPEPOL	JK'	0.5	P0	LF	LF1	out	Woll	JK'	0.5	P0	60
SPEPOL	JK'	0.5	P45	LF	LF1	out	Woll	JK'	0.5	P45	60
SPEPOL	JK'	0.75	P0	LF	LF1	out	Woll	JK'	0.75	P0	60
SPEPOL	JK'	0.75	P45	LF	LF1	out	Woll	JK'	0.75	P45	60
SPEPOL	JK'	1.0	P0	LF	LF1	out	Woll	JK'	1.0	P0	60
SPEPOL	JK'	1.0	P45	LF	LF1	out	Woll	JK'	1.0	P45	60
SPEPOL	JK'	1.5	P0	LF	LF1	out	Woll	JK'	1.5	P0	60
SPEPOL	JK'	1.5	P45	LF	LF1	out	Woll	JK'	1.5	P45	60
SPEPOL	JK'	2.0	P0	LF	LF1	out	Woll	JK'	2.0	P0	60
SPEPOL	JK'	2.0	P45	LF	LF1	out	Woll	JK'	2.0	P45	60
SPEPOL	JK'	none	P0	LF	LF1	out	Woll	JK'	SF	P0	60
SPEPOL	JK'	none	P45	LF	LF1	out	Woll	JK'	SF	P45	60
SPEPOL	HK	0.5	P0	LF	LF1	out	Woll	HK	0.5	P0	60
SPEPOL	HK	0.5	P45	LF	LF1	out	Woll	HK	0.5	P45	60
SPEPOL	HK	0.75	P0	LF	LF1	out	Woll	HK	0.75	P0	60
SPEPOL	HK	0.75	P45	LF	LF1	out	Woll	HK	0.75	P45	60
SPEPOL	HK	1.0	P0	LF	LF1	out	Woll	HK	1.0	P0	60
SPEPOL	HK	1.0	P45	LF	LF1	out	Woll	HK	1.0	P45	60
SPEPOL	HK	1.5	P0	LF	LF1	out	Woll	HK	1.5	P0	60
SPEPOL	HK	1.5	P45	LF	LF1	out	Woll	HK	1.5	P45	60
SPEPOL	HK	2.0	P0	LF	LF1	out	Woll	HK	2.0	P0	60
SPEPOL	HK	2.0	P45	LF	LF1	out	Woll	HK	2.0	P45	60
SPEPOL	HK	none	P0	LF	LF1	out	Woll	HK	SF	P0	60
SPEPOL	HK	none	P45	LF	LF1	out	Woll	HK	SF	P45	60
SPEPOL	viewS	0.5	P0	LF	LF1	out	open	SW	0.5	P0	20
SPEPOL	viewS	0.5	P45	LF	LF1	out	open	SW	0.5	P45	20
SPEPOL	viewS	0.75	P0	LF	LF1	out	open	SW	0.75	P0	20
SPEPOL	viewS	0.75	P45	LF	LF1	out	open	SW	0.75	P45	20
SPEPOL	viewS	1.0	P0	LF	LF1	out	open	SW	1.0	P0	20
SPEPOL	viewS	1.0	P45	LF	LF1	out	open	SW	1.0	P45	20
SPEPOL	viewS	1.5	P0	LF	LF1	out	open	SW	1.5	P0	20
SPEPOL	viewS	1.5	P45	LF	LF1	out	open	SW	1.5	P45	20
SPEPOL	viewS	2.0	P0	LF	LF1	out	open	SW	2.0	P0	20
SPEPOL	viewS	2.0	P45	LF	LF1	out	open	SW	2.0	P45	20
SPEPOL	viewS	none	P0	LF	LF1	out	open	SW	SF	P0	20
SPEPOL	viewS	none	P45	LF	LF1	out	open	SW	SF	P45	20
SPEPOL	viewK	0.5	P0	LF	LF1	out	K	open	0.5	P0	20
SPEPOL	viewK	0.5	P45	LF	LF1	out	K	open	0.5	P45	20
SPEPOL	viewK	0.75	P0	LF	LF1	out	K	open	0.75	P0	20
SPEPOL	viewK	0.75	P45	LF	LF1	out	K	open	0.75	P45	20
SPEPOL	viewK	1.0	P0	LF	LF1	out	K	open	1.0	P0	20
SPEPOL	viewK	1.0	P45	LF	LF1	out	K	open	1.0	P45	20

SPEPOL	viewK	1.5	P0	LF	LF1	out	K	open	1.5	P0	20
SPEPOL	viewK	1.5	P45	LF	LF1	out	K	open	1.5	P45	20
SPEPOL	viewK	2.0	P0	LF	LF1	out	K	open	2.0	P0	20
SPEPOL	viewK	2.0	P45	LF	LF1	out	K	open	2.0	P45	20
SPEPOL	viewK	none	P0	LF	LF1	out	K	open	SF	P0	20
SPEPOL	viewK	none	P45	LF	LF1	out	K	open	SF	P45	20
#-----											
# high resolution spectroscopy: SPEHR grism slit											
#											
SPEHR	dark	0.5		LF	any	any	close	any	any	any	60
SPEHR	dark	0.75		LF	any	any	close	any	any	any	60
SPEHR	dark	1.0		LF	any	any	close	any	any	any	60
SPEHR	dark	1.5		LF	any	any	close	any	any	any	60
SPEHR	dark	2.0		LF	any	any	close	any	any	any	60
SPEHR	dark	none		LF	any	any	close	any	any	any	60
SPEHR	1mic	0.5		LF	LF1	out	1mic	J4	0.5	open	60
SPEHR	1mic	0.75		LF	LF1	out	1mic	J4	0.75	open	60
SPEHR	1mic	1.0		LF	LF1	out	1mic	J4	1.0	open	60
SPEHR	1mic	1.5		LF	LF1	out	1mic	J4	1.5	open	60
SPEHR	1mic	2.0		LF	LF1	out	1mic	J4	2.0	open	60
SPEHR	1mic	none		LF	LF1	out	1mic	J4	LF	open	30
SPEHR	Jn	0.5		LF	LF1	out	Jn	J4	0.5	open	60
SPEHR	Jn	0.75		LF	LF1	out	Jn	J4	0.75	open	60
SPEHR	Jn	1.0		LF	LF1	out	Jn	J4	1.0	open	60
SPEHR	Jn	1.5		LF	LF1	out	Jn	J4	1.5	open	60
SPEHR	Jn	2.0		LF	LF1	out	Jn	J4	2.0	open	60
SPEHR	Jn	none		LF	LF1	out	Jn	J4	LF	open	30
SPEHR	J	0.5		LF	LF1	out	J	J4	0.5	open	60
SPEHR	J	0.75		LF	LF1	out	J	J4	0.75	open	60
SPEHR	J	1.0		LF	LF1	out	J	J4	1.0	open	60
SPEHR	J	1.5		LF	LF1	out	J	J4	1.5	open	60
SPEHR	J	2.0		LF	LF1	out	J	J4	2.0	open	60
SPEHR	J	none		LF	LF1	out	J	J4	LF	open	30
SPEHR	H	0.5		LF	LF1	out	H	J4	0.5	open	60
SPEHR	H	0.75		LF	LF1	out	H	J4	0.75	open	60
SPEHR	H	1.0		LF	LF1	out	H	J4	1.0	open	60
SPEHR	H	1.5		LF	LF1	out	H	J4	1.5	open	60
SPEHR	H	2.0		LF	LF1	out	H	J4	2.0	open	60
SPEHR	H	none		LF	LF1	out	H	J4	LF	open	20
#											
# Alternativa da considerare											
#											
# SPEHR	H	0.5		LF	LF1	out	H	K3	0.5	open	60

The file motor2.pos contains:

```
# 0= negative limit switch; other limit switch at ~ 8500
#
LF1 2300
SF1 6800
PR1 2600
```

The file motor3.pos contains:

```
#
# Tutte le posizioni in steps riferite ad un Reset-
#
# Il laser allineato sul collimatore tocca il bordo (si inizia a vedere
# sull'array) a 27300 steps
#
      out          0
      in          35000
```

The file motor4.pos contains:

```
# 60000 step = complete revolution of filter wheel
#
# IMPORTANTE: tutti i valori sotto sono riferiti a Reset-
#
# 23/5/2000 : determinato centro posizione aperta come media dei bordi
#             dove si vignetta il laser allineato sul collimatore
#             start=7350 end=9660 => center=8505
# 24/5/2000 : corretti tutti valori accordingly
#
#      nome          step          giri          deg
#
      grey5          2813          2.8128          16.88
      grey9          5659          5.6590          33.95
      open           8505          8.5050          51.03
      close          11351         11.3510         68.11
      K              14197         14.1972         85.18
      K'             17043         17.0432         102.26
      H              19889         19.8893         119.34
      J              22735         22.7353         136.41
      Jn             25582         25.5815         153.49
      1mic           28428         28.4275         170.57
      Woll           31390         31.3898         188.34
      cut19          34352         34.3522         206.11
```


Brg	37198	37.1982	223.19
Kcont	40044	40.0443	240.27
FeII	42890	42.8903	257.34
Hcont	45737	45.7365	274.42
H2*	48582	48.5825	291.49
CH4_s*	51429	51.4287	308.57
CH4_l*	54275	54.2747	325.65
# HK'*	57121	57.1990	343.19
#			
# K_flat e' quello in piano, per l'allineamento			
#			
Kflat	57121	57.1207	342.72
Ge	59967	59.9668	359.80
# Z*	59967	59.9668	359.80

The file motor5.pos contains:

# 60000 step = 1 complete revolution of grism wheel			
# nome	step	giri	deg
#			
K'	1250	1.2500	7.50
close	4542	4.5425	27.25
JH	8126	8.1257	48.75
J4	11709	11.7088	70.25
SW	15292	15.2920	91.75
JK'	18875	18.8752	113.25
Woll	22458	22.4582	134.75
HK	26041	26.0413	156.25
IJ	29624	29.6245	177.75
K3	33208	33.2077	199.25
grey9	36791	36.7908	220.74
IK*	40374	40.3740	242.24
grey5	43957	43.9572	263.74
Free	47540	47.5402	285.24
Amici	51539	51.5387	309.23
open	55246	55.2463	331.48
focus	58248	58.2482	349.49

The file motor6.pos contains:

# 200000 step = 1 complete revolution of aperture wheel			
# nome	step	giri	deg
#			
Mask	7005	7.0050	12.61

1.5	28717	28.7172	51.69
0.75	50429	50.4294	90.77
LF	72141	72.1411	129.85
2.0	93853	93.8533	168.94
SF	115566	115.5656	208.02
1.0	137278	137.2778	247.10
U5	149249	149.2489	268.65
U4	154093	154.0928	277.37
U3	158937	158.9367	286.09
close	163780	163.7800	294.80
U2	168624	168.6239	303.52
U1	173468	173.4678	312.24
0.5	185293	185.2928	333.53

The file motor7.pos contains:

```
#      nome      step      giri      deg
#
      open        0      0.0000      0.00
      P0      25000      25.0000      45.00
      P45      47222      47.2222      85.00
```

1.5.3 Imaging List Menus

For the *Normal Imaging* the setting of three devices, controlled by next three files must be done.

The file IMA_1.menu:

```
#
# Imaging (IMA) mode
#
# Menu to pop-up when key "filter" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description      Command  Second comment/warning
#
# Broad band filters
#
```

```

"1mic    (0.96-1.10)"    1mic
"Jn      (1.17-1.33)"    Jn
"J       (1.10-1.39)"    J      "J has lower efficiency than Jn"
"H       (1.48-1.78)"    H
"K'      (1.95-2.30)"    K'
"K       (2.02-2.36)"    K
#"Ks     (2.02-2.30)"    Ks     "Ks cannot be used with grey filters"
#"HK'    (1.47-2.30)"    HK'
"SW      (0.90-1.80)"    SW     "SW is meant for deep imaging, not for photomet
----- #end of broad band filters list
#"          "
#
#-Medium band filters
#
#"Zn     (0.996-1.069)"    Zn
#"CH4s   (1.530-1.630)"    CH4s
#"CH4l   (1.640-1.740)"    CH4l
#
#----- #end of medium band filters list
# Narrow band filters
#
#"          "
"Brg     (2.150-2.182)"    Brg
#"H2     (2.106-2.138)"    H2
"Kcont   (2.253-2.287)"    Kcont
"FeII    (1.632-1.656)"    FeII
"Hcont   (1.558-1.582)"    Hcont
----- #end of narrow band filters list
#
"Dark          "    dark
----- # End of standard modes
#
# Maialate di Tino
#
"Open          "    open
===== #end of file

```

The file IMA_2.menu:

```

#
# Imaging (IMA) mode
#
# Menu to pop-up when key "objective" is hit.
#

```

```

# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
"LF (0.25\"/pix)"      LF
"SF (0.13\"/pix)"      SF
#
# Queste sono alternative su come dare l'informazione sul campo.
#
#"LF (4.2'x4.2')"
#"SF (2.2'x2.2')"
#"LF (4.2'x4.2' 0.25\"/pix)"
#"SF (2.2'x2.2' 0.13\"/pix)"
===== end

```

The file IMA_3.menu:

```

#
# Imaging (IMA) mode
#
# Menu to pop-up when key "attenuator" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
"None  "              G0
"5 magnitudes "       G5
"10 magnitudes "      G10
===== end =====

```

For the *Imaging & Polarimetry* mode the following two files are used for the corresponding settings:

The file IMAPOL_1.menu:

```

#
# Imaging-polarimetry (IMAPOL) mode
#
# Menu to pop-up when key "filter" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 min)
#
# Description          Command  Second comment/warning
#
#-- Broad band filters
#
"1mic  (0.96-1.10)"    1mic
"Jn    (1.17-1.33)"    Jn
"J     (1.10-1.39)"    J      "J has lower efficiency than Jn"
"H     (1.48-1.78)"    H
"K'    (1.95-2.30)"    K'
"K     (2.02-2.36)"    K
#"HK'  (1.47-2.30)"    HK'
"SW    (0.90-1.80)"    SW  "SW is meant for deep imaging, not for photomet
#"          "
#
#----- Medium band filters (use different colours?)
#
#"Zn    (0.996-1.069)"    Zn
#"CH4s  (1.530-1.630)"    CH4s
#"CH41  (1.640-1.740)"    CH41
#
-- Narrow band filters
#
#"          "
"Brg    (2.150-2.182)"    Brg
#"H2    (2.106-2.138)"    H2
"Kcont  (2.253-2.287)"    Kcont
"FeII   (1.632-1.656)"    FeII
"Hcont  (1.558-1.582)"    Hcont
#
-----
"Dark          "    dark

```

```
=====end =====
```

The file IMAPOL_2.menu:

```
#
# Imaging-polarimetry (IMAPOL) mode
#
# Menu to pop-up when key "wl/2 plate" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
" 0 degrees  "          P0
"45 degrees  "          P45
=====end=====
```

1.5.4 Spectrometry List Menus

The *Spectrometry* mode has three sub-modes — *Low Resolution*, *High Resolution* and *Spectrometry & Polarimetry*.

For the *Low Resolution* observation mode there are three files with menus.

The file SPELR_1.menu:

```
#
# Spectroscopy Low Resolution (SPELR) mode
#
# Menu to pop-up when key "grism" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
#"Amici (0.80-2.50)"  AMICI      "Be careful with differential refraction!"
```

```

"Amici (0.80-2.50)" AMICI
"IJ (0.88-1.45)" IJ
"JH (1.10-1.75)" JH
"JK' (1.15-2.30)" JK'
"HK (1.65-2.50)" HK
-----
"Slit view blu (SW)" viewS
"Slit view red (K) " viewK
-----
"Dark " dark
=====end=====

```

The file SPELR_2.menu:

```

#
# Spectroscopy Low Resolution (SPELR) mode
#
# Menu to pop-up when key "slit" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 min)
#
# Description          Command  Second comment/warning
#
"0.5\" " "          0.5
"0.75\" " "        0.75
"1.0\" " "          1.0
"1.5\" " "          1.5
"2.0\" " "          2.0
-----
"Slitless"           none
=====end=====

```

The file SPELR_3.menu:

```

#
# Spectroscopy Low Resolution (SPELR) mode
#
# Menu to pop-up when key "attenuator" is hit.
#

```

```

# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
"None  "              G0
"5 magnitudes "      G5
"10 magnitudes "     G10
=====end=====

```

For the *High Resolution* observation mode there are two files.
The file SPEHR_1.menu:

```

#
# Spectroscopy High Resolution (SPEHR) mode
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
"1mic  (0.96-1.10)"   1mic
"Jn    (1.17-1.33)"   Jn
"J     (1.10-1.39)"   J      "J has lower efficiency than Jn"
"H     (1.48-1.78)"   H
"K'    (1.95-2.30)"   K'
"K     (2.02-2.36)"   K
"Kbroad (1.93-2.36)" Kb      "Kbroad has lower efficiency than K, K'"
"Klong (2.20-2.50)"  Klong
-----
"Slit view blu (SW)" viewS
"Slit view red (K) " viewK
-----
"Dark          "      dark
=====end=====

```

The file SPEHR_2.menu:


```

#
# Spectroscopy High Resolution (SPEHR) mode
#
# Menu to pop-up when key "slit" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 min)
#
# Description          Command  Second comment/warning
#
"0.5\" "              0.5
"0.75\" "            0.75
"1.0\" "             1.0
"1.5\" "             1.5
"2.0\" "             2.0
-----
"Slitless"           none
=====end=====

```

And, finally, there are three menus for the *Spectrometry & Polarimetry* observation mode.

The file SPEPOL_1.menu:

```

#
# Spectro-polarimetry (SPEPOL) mode
#
# Menu to pop-up when key "grism" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 min)
#
# Description          Command  Second comment/warning
#
#"Amici (0.80-2.50)"  AMICI    "Be careful with differential refraction!"
"Amici (0.80-2.50)"  AMICI
"IJ (0.88-1.45)"     IJ

```

```

"JH      (1.10-1.75)"   JH
"JK'     (1.15-2.30)"   JK'
"HK      (1.65-2.50)"   HK
-----
"Slit view blu (SW)"   viewS
"Slit view red (K) "   viewK
-----
"Dark           "      dark
=====end=====

```

The file SPEPOL_2.menu:

```

#
# Spectro-polarimetry (SPEPOL) mode
#
# Menu to pop-up when key "slit" is hit.
#
# Description appears in the menu
#
# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 minute)
#
# Description          Command  Second comment/warning
#
"0.5\"  "              0.5
"0.75\" "              0.75
"1.0\"  "              1.0
"1.5\"  "              1.5
"2.0\"  "              2.0
-----
"Slitless"           none
=====end=====

```

The file SPEPOL_3.menu:

```

#
# Spectro-polarimetry (SPEPOL) mode
#
# Menu to pop-up when key "wl/2 plate" is hit.
#
# Description appears in the menu
#

```

```

# Command is the keyword to search in the file with setup of observing-modes
#
# Second comment/warning should appear/pop-up in a separate window when the
# grism is selected (this comment/warning should then disappear after ~1 min)
#
# Description          Command  Second comment/warning
#
" 0 degrees  "          P0
"45 degrees  "          P45
=====end=====

```

1.6 Software Compilation

The `src` directory contains the source files of the software.

The compilation process is supported by standard programming tool **make**. Source texts for both parts of the software are placed into two corresponding sub-directories (`xnics` and `nicsgate`) of the top source directory (`src`). The `src` directory has a file `Makefile`. The sub-directories contain the source files of the corresponding parts of the software. The files generally contain the programm material for the support of one certain task or the small number connected tasks and have indicative names. As usually, there are some miscellaneous routines which are typically in the file with the name `xutil.c`. Each part of the software can be compiled independently using **make**. For the compilation is used free distributed broadly available GNU `gcc` compiler. After the compilation both modules, `xnics` and `NICSGate` are moved to the `bin` directory.

The `xnics` uses the standard `C` and `X11R6` libraries, including 3D library of Athena Widget Set. Obviously, the standard version of this library can be used influencing only a little bit the widgets look.

The `nicsgate` uses additionally support for the fits files maintenance, provided by `libfitscio.a`. This library should reside in the `/usr/local/lib` directory. If it for some reasons is lost, there is its copy in the `tmp` directory of the `xnics` file system. There are also the corresponding `headers`, which should reside in the `/usr/local/include` directory. The special driver is used for the support of the `transnix link`. The files `link.c` and `link.h` should be placed in the proper system directory.

There is also the sub-directory `subtract` with auxiliary programs. Their compilation is also supported by `make`. The binary modules are copied automatically into the `bin` directory.

The `transnix` contains all the material of the OCCAM program residing in the transputer network of the NICS electronics. We do not describe its compilation here.

Chapter 2

Instruments Tuning

To provide the instrument developers by the means to investigate the difficult situations and to tune the different parameters of the instruments, there is a special *debug mode* of the *xnics*.

The *NICSgate Debug Monitor* can be started from *Setup* menu (Fig. 2.1).

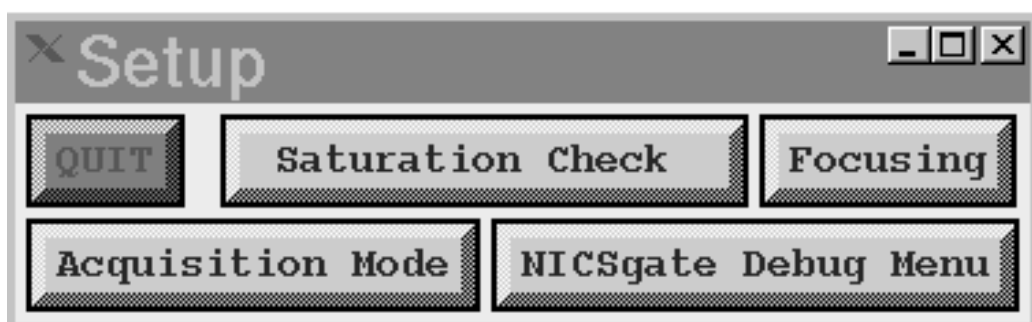


Figure 2.1: Setup Xnics Menu

The widget with *NICSgate Debug Monitor* menu (Fig. 2.2) will be popped-up. **This menu is intended only for software maintenance and the instruments tuning.**

2.1 NICSgate Debug Monitor

There are many options provided by the *NICSgate Debug Monitor*. Some of them concern the NICS electronics, or, better, the program which controls it, the *transnix*.

The user can boot into the NICS electronics the chosen binary image of the program. To this end the absolute path to the desired binary module should be provided and then the corresponding button should be pressed.

It is possible to reset the link to the electronics in the case of the problems with its driver. When the booted program does not work correctly it is a

usual situation. To execute the another boot, it is necessary first to reset the link (the driver).

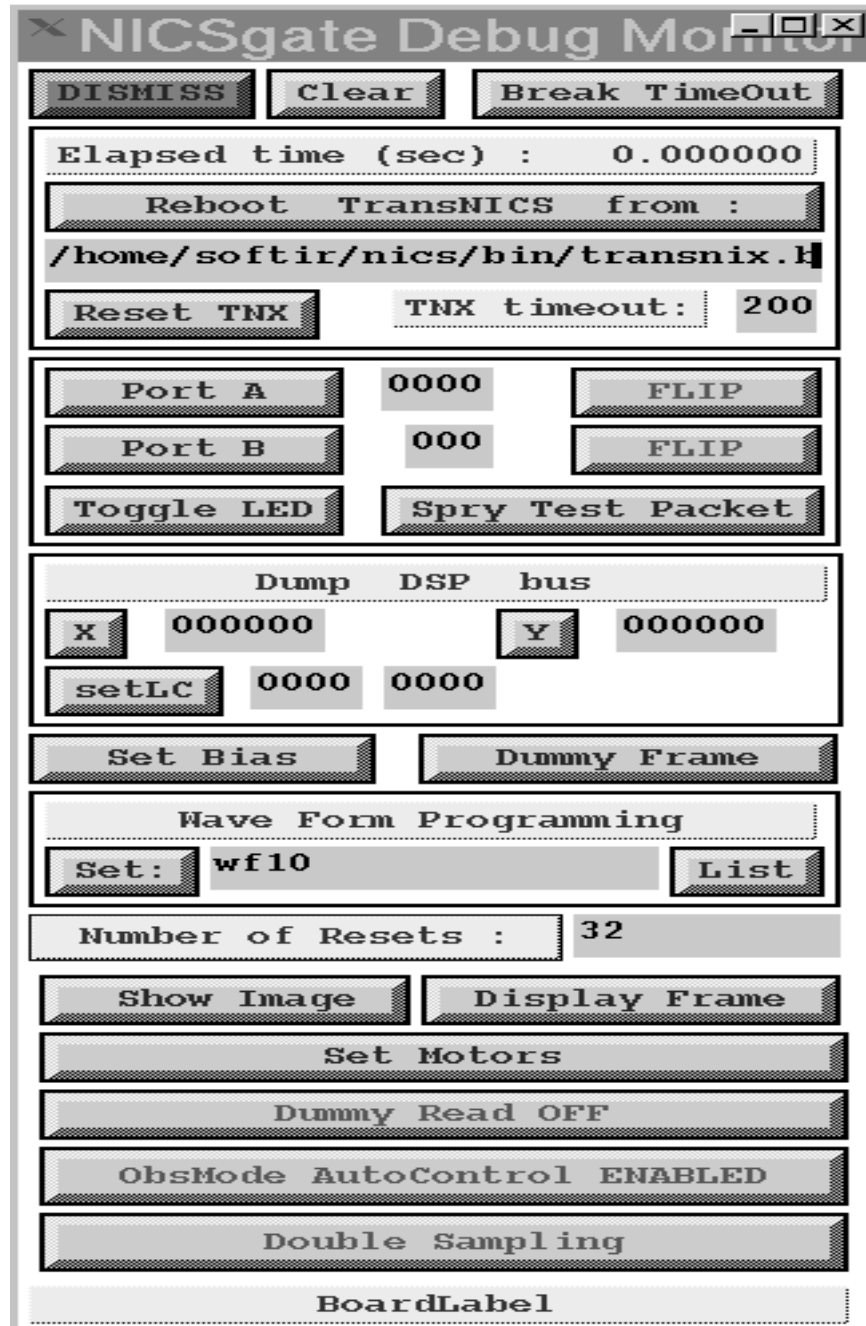


Figure 2.2: The NICSGate Debug Monitor Widget

There is the possibility to change the timeout, which is used to control from the *xnics* side the flow of the transnix events. It is an important parameter for the overall functionality of the software. On its correct value

depends the stability of the events processing.

The next panel is intended to permit the several actions on the different internal parts of the NICS electronics. It is possible to set the desirable value for both internal ports, **A** and **B**, and to initiate on each of them the “flip” process - the change of the chosen for the port setting every two seconds to the complimentary state. For this purpose the the masks 0x7FFF for the Port A and 0xFFFF for the Port B are used. **To stop the “flip” process the user should use the button `Break TimeOut`**. All other buttons during the “flip” process are insensitive. The value for each port can be written in the corresponding text window. To send the command to execute the chosen setting it is necessary to click on the corresponding button `Port A` or `Port B`.

The user also can send the commands to toggle the electronics LED by the button `Toggle LED`, and to spray the test packet through the transputer network by the button `Spray Test Packet`.

Then there is the possibility to dump the **X** and **Y** registers of the DSP and set the LC value.

The button `Set Bias` pops-up the menu for the bias setting (Section 2.2).

The button `Dummy Frame` sends a request to the *transnix* to send back the dummy image. It can be used to check the correctness of the data transmission from *transnix* to *xnics*.

The image can be immediately (after receiving, of course) analyzed using the internal viewer. It can be popped-up by the `Show Image` button. There is also the possibility to use the facilities of the external viewer from `Display Frame`[3].

The button `Set Motors` pops-up the corresponding menu (Section 2.3).

There is the panel which permits to load into the electronics any desirable *WaveForm*. The waveform file name should have an extension `.inp`. This name (without extension) can be written in the panel text window or chosen from the list of the corresponding resource directory (`resource/waveforms`) contents, accessible through the `List` button. To load the chosen file one should click on the button `Set:`.

Some parameters of the *integration* command (the command which sets the parameters of the data acquisition and starts them,[5]), can be changed too. Among them there is the *Number of Resets* before the integration. By default *xnics* uses 32. Then there is *Dummy Read* flag, which can be set **Off** (default) or **On**. The corresponding button changes its color for different setting. Another two-values parameter is `Double Sampling` (default) or `Single Sampling`.

Note.

- When there are done the changes through the *NICSGate Debug Monitor*, the normal way of the *xnics* session is modified. So the most of its normal functionality is not accessible. *Xnics* returns to its normal proceeding when the *NICSGate Debug Monitor* menu is closed. It could be very inconvenient. To resolve this problem may be used the button `Clear`. The following rule should be used: first do the necessary setting, etc., using the *NICSGate Debug Monitor* then click on the button `Clear`. The *xnics* is turned to its standard functionality and any normal acquisition task can be executed.
- Any new activity on the *NICSGate Debug Monitor* menu (except the innocent pop-up of the sub-menus and the text writing) again preclude the normal task execution.

Another problem of the similar origin comes when the motors are set **manually** through the corresponding menu (2.3). The standard way of *xnics* to control the motors is too very restrictive. **No non-standard positions are permitted.** *Xnics* **always** sets the motors positions in the correspondence with the chosen *Observation Mode*. And **without the complete settings** for the given *Observation Mode* mode the acquisition task **can not be started**.

To permit the data acquisition **at any motors positions** there is the two-values button, having a label `ObsMode AutoControl ENABLED`, which can be changed to `ObsMode AutoControl DISABLED`. It changes also the color when pressed.

2.2 Bias Setting

The Fig. 2.3 presents the menu intended for the interactive bias setting. **Note**, that the real setting is executed only when the corresponding **button** is pressed. The change of the value in the text windows does not change the settings in the NICS electronics.

This menu permits to tune the biases and the polarimeter tensions for the better functionality of the NICS. Usually after the change of the parameter the acquisition should be done, the resulting image controlled and so on.

2.3 Motors in Debug Mode

For the development of the instrument and the tuning of its functionalities it is necessary to have the possibilities to move any motor to any possible position and, probably, to make the data acquisition in this non-standard



Figure 2.3: Bias Setting Menu

environment. For this purpose the *Motor's Control* menu (Fig. 2.4) provides the possibility to set any position of the chosen motor and to make its reset in positive or negative directions. Also any valid motor controller command can be send to it by the direct definition.

The upper pair, the button `Send Any Serial Command:` and the adjacent text window should be used to compound the desirable command from the valid set [6] and then send it to the motor controller. Some useful commands are presented below:

- **G** : start the movements of all motors. The destination should be set before.

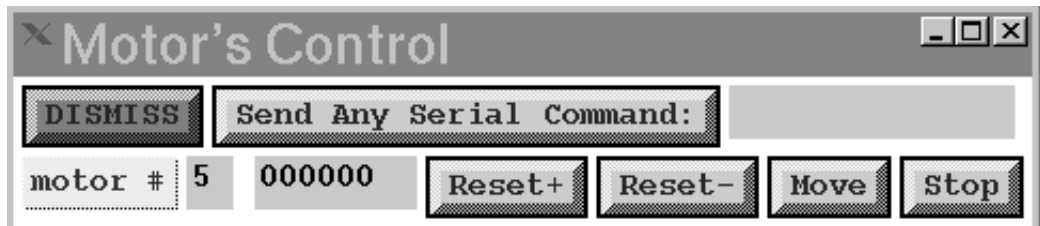


Figure 2.4: The menu for the Manual Control of the Motors

- **S** : stop the movements of all motors.
- **PR** : report the positions of all motors. In form **#PR**, where **#** is any number from 1 to 7, reports the position of the only mentioned motor.
- **R** : report the statuses of all motors. The form for a single motor is as mentioned above.

The message widget with results of the command execution and with received response of the motor controller, when it was interrogated, is normally popped-up. The *xnics* tries to maintain always the correct internal state of the motors, including their positions. Because of this the certain level of the attention is needed. While the user can think that he/she has issued a single command, when the issued command changes the motor position, the additional command, asking the resulting position is send automatically. The command (movement) execution time could be long (even minutes), thus the user can send another and another command. This can create some break in the internal protocol, because only finite (and small) number of such, practically incorrect, commands can be supported effectively. It is not fatal, but may be misleading. Thus, **do not send the next command before you are sure that the previous is executed**. If the several motors should be moved simultaneously, first set their positions and then start their movements by the command **G**.

The line of the fields at the bottom of the menu provides the usual set of the actions on a single chosen motor. There is the field for the motor number definition. Then follows the text field for the desired position (in motor steps), and the set of the buttons **Reset+**, **Reset-**, **Move** and **Stop**. Their meaning is obvious from the labels.

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